



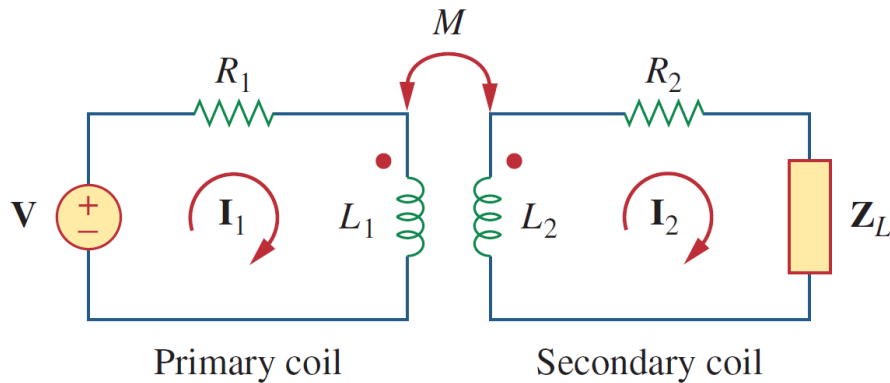
## Lecture – 13

Date: 26.09.2016

- Transformer

## Transformer

A **transformer** is generally a four-terminal device comprising two (or more) magnetically coupled coils.



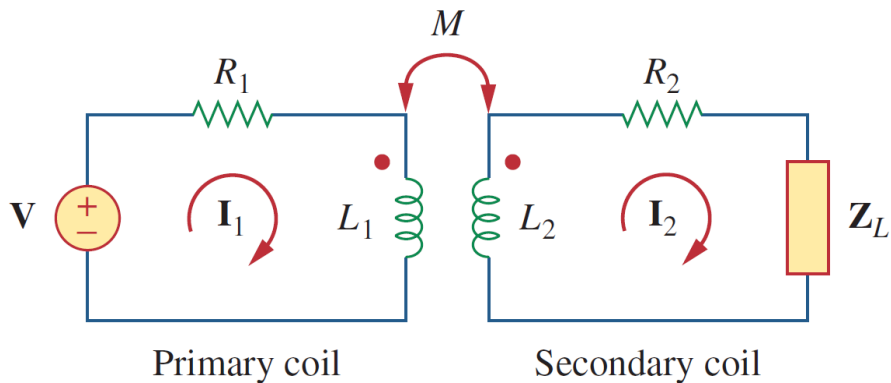
- The resistances  $R_1$  and  $R_2$  account for the losses (power dissipation) in the coils.

- The transformer is *linear* if the coils are wound on a magnetically linear material—a material for which the magnetic permeability is constant. Such materials include air, plastic, Bakelite, and wood.
- In fact, most materials are magnetically linear.

A linear transformer may also be regarded as one whose flux is proportional to the currents in its windings.

Linear transformers are sometimes called *air-core transformers*, although not all of them are necessarily air-core.

## Transformer (contd.)



$$V = (R_1 + j\omega L_1)I_1 - j\omega M I_2$$

$$0 = -j\omega M I_1 + (R_2 + j\omega L_2 + Z_L)I_2$$

- the input impedance  $Z_{in}$  as seen from the source:

$$Z_{in} = \frac{V}{I_1} = R_1 + j\omega L_1 + \frac{\omega^2 M^2}{R_2 + j\omega L_2 + Z_L}$$

primary impedance

due to the coupling between the primary and secondary windings

It is as though this impedance is reflected to the primary and is called *reflected impedance*  $Z_R$

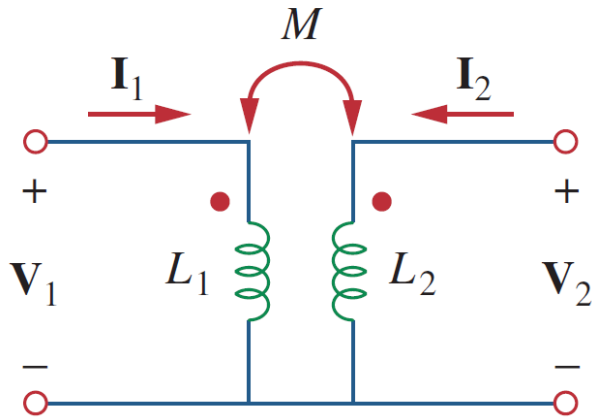
$$Z_R = \frac{\omega^2 M^2}{R_2 + j\omega L_2 + Z_L}$$



Not affected by the location of the dots on the transformer

## Transformer (contd.)

- it is sometimes convenient to replace a magnetically coupled circuit by an equivalent circuit with no magnetic coupling.

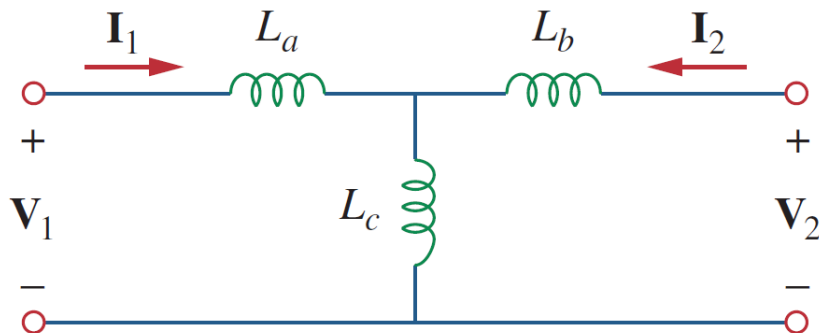


$$\begin{bmatrix} \mathbf{V}_1 \\ \mathbf{V}_2 \end{bmatrix} = \begin{bmatrix} j\omega L_1 & j\omega M \\ j\omega M & j\omega L_2 \end{bmatrix} \begin{bmatrix} \mathbf{I}_1 \\ \mathbf{I}_2 \end{bmatrix}$$

**Matrix Inversion**

$$\begin{bmatrix} \mathbf{I}_1 \\ \mathbf{I}_2 \end{bmatrix} = \begin{bmatrix} \frac{L_2}{j\omega(L_1L_2 - M^2)} & \frac{-M}{j\omega(L_1L_2 - M^2)} \\ \frac{-M}{j\omega(L_1L_2 - M^2)} & \frac{L_1}{j\omega(L_1L_2 - M^2)} \end{bmatrix} \begin{bmatrix} \mathbf{V}_1 \\ \mathbf{V}_2 \end{bmatrix}$$

## For a T-Network



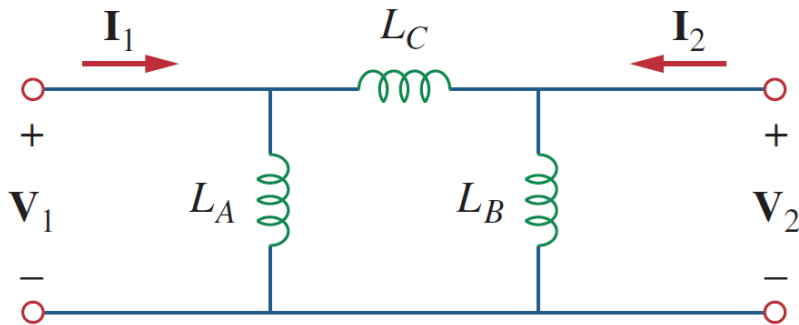
$$\begin{bmatrix} \mathbf{V}_1 \\ \mathbf{V}_2 \end{bmatrix} = \begin{bmatrix} j\omega(L_a + L_c) & j\omega L_c \\ j\omega L_c & j\omega(L_b + L_c) \end{bmatrix} \begin{bmatrix} \mathbf{I}_1 \\ \mathbf{I}_2 \end{bmatrix}$$

## Transformer (contd.)

- For the T-model to be equivalent to the linear transformer:

$$L_a = L_1 - M, \quad L_b = L_2 - M, \quad L_c = M$$

### For a $\pi$ -Network



$$\begin{bmatrix} \mathbf{I}_1 \\ \mathbf{I}_2 \end{bmatrix} = \begin{bmatrix} \frac{1}{j\omega L_A} + \frac{1}{j\omega L_C} & -\frac{1}{j\omega L_C} \\ -\frac{1}{j\omega L_C} & \frac{1}{j\omega L_B} + \frac{1}{j\omega L_C} \end{bmatrix} \begin{bmatrix} \mathbf{V}_1 \\ \mathbf{V}_2 \end{bmatrix}$$

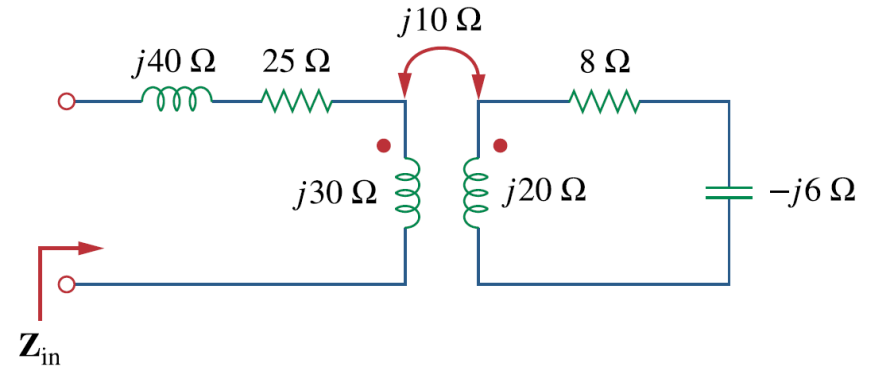
- For the  $\pi$ -model to be equivalent to the linear transformer:

$$L_A = \frac{L_1 L_2 - M^2}{L_2 - M}, \quad L_B = \frac{L_1 L_2 - M^2}{L_1 - M}, \quad L_C = \frac{L_1 L_2 - M^2}{M}$$

**In the T- and  $\pi$ - Models, the inductors are not magnetically coupled**

## Example – 1

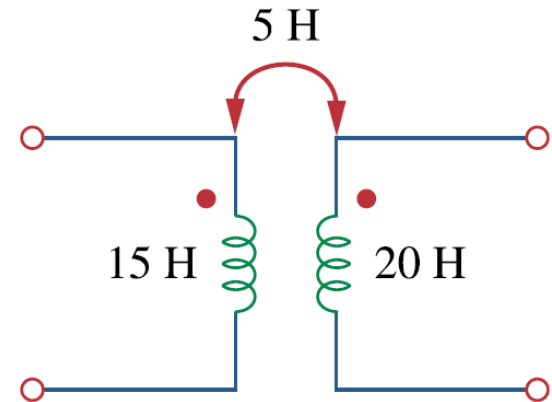
- (a) Find the input impedance of the circuit using the concept of reflected impedance.
- (b) Obtain the input impedance by replacing the linear transformer by its T equivalent.



## Example – 2

Find:

- (a) the  $T$ -equivalent circuit,  
 (b) the  $\pi$ -equivalent circuit.



## Example – 3

Two linear transformers are cascaded as shown below. Show:

$$\mathbf{Z}_{in} = \frac{\omega^2 R(L_a^2 + L_a L_b - M_a^2 + j\omega^3(L_a^2 L_b + L_a L_b^2 - L_a M_b^2 - L_b M_a^2))}{\omega^2(L_a L_b + L_b^2 - M_b^2) - j\omega R(L_a + L_b)}$$

