

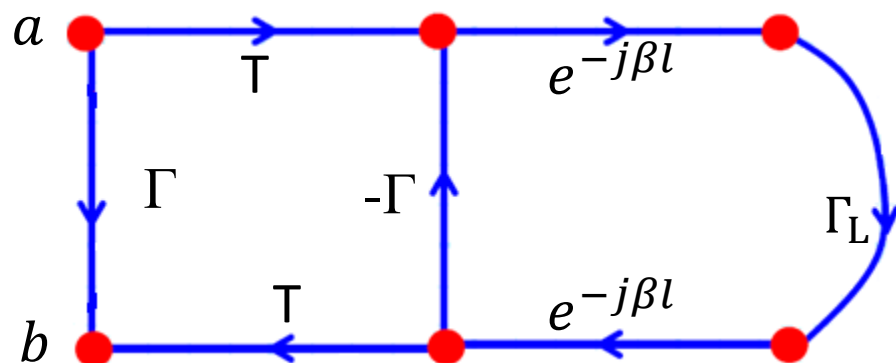
Lecture – 16

Date: 09.10.2014

- Frequency Response of Quarter Wave Transformer
- Multi-Section Transformer
- Binomial Multi-section Transformer
- Chebyshev Multi-section Transformer
- Tapered Lines

Frequency Response of a $\lambda/4$ Matching Network

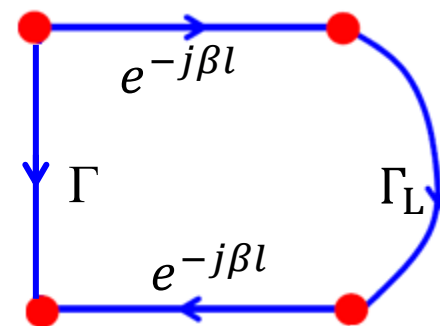
Q: You have once again provided us with **confusing** and perhaps useless information. The quarter-wave matching network has an **exact** SFG of:



Using our **reduction rules**, we can **quickly** conclude that:

$$\Gamma_{in} \doteq \frac{b}{a} = \Gamma + \frac{T^2 \Gamma_L e^{-j2\beta l}}{1 - \Gamma \Gamma_L}$$

- You could have left this **simple** and **precise** analysis **alone**— BUT **NOOO!!**
- **You** had to foist upon us a long, **rambling** discussion of “the propagation series” and “direct paths” and “the theory of small reflections”, culminating with the **approximate** (i.e., less accurate!) SFG:



Freq. Response of a $\lambda/4$ Matching Network (contd.)

- From the approximate SFG we were able to conclude the **approximate** (i.e., less accurate!) result:

$$\Gamma_{in} \doteq \frac{b}{a} = \Gamma + \Gamma_L e^{-j2\beta l}$$

The **exact** result was **simple**—and **exact**! **Why** did you make us determine this **approximate** result?

A: In a word: frequency response*. * OK, two words.

the **mathematical form** of the result is much simpler to **analyze** and/or **evaluate** (e.g., no **fractional** terms!).

Q: What exactly would we be analysing and/or evaluating?

A: The **frequency response** of the matching network, for one thing.

Remember, all matching networks must be **lossless**, and so must be made of **reactive** elements (e.g., lossless transmission lines). The impedance of every reactive element is a **function of frequency**, and so too then is Γ_{in} .

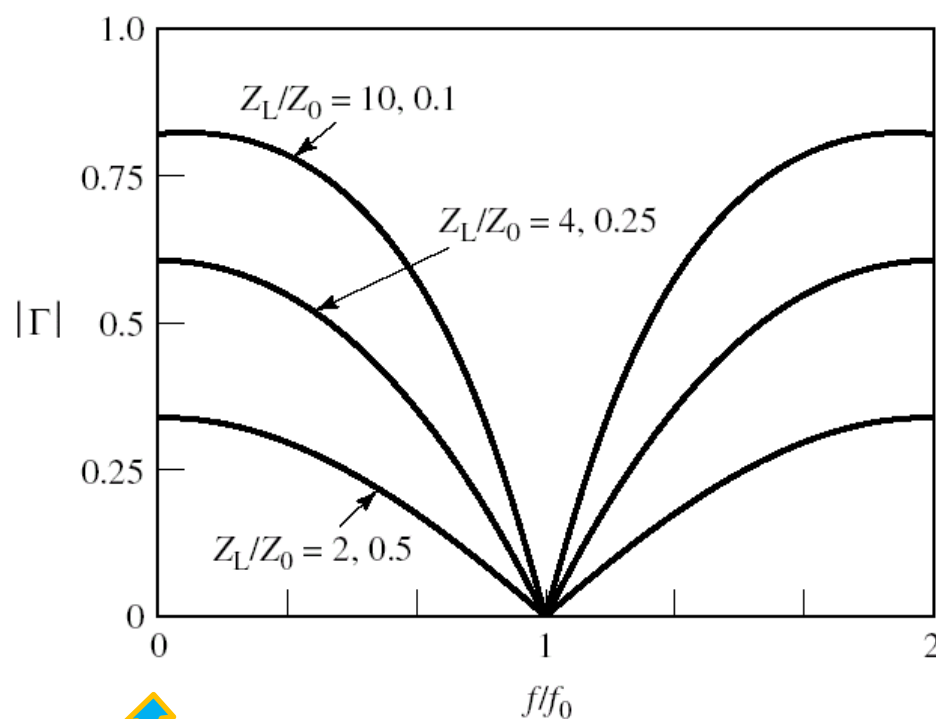
Freq. Response of a $\lambda/4$ Matching Network (contd.)



Say we wish to determine function $\Gamma_{in}(\omega)$.

Q: Isn't $\Gamma_{in}(\omega) = 0$ for a quarter wave matching network?

A: Oh my gosh **no!** A properly designed matching network will typically result in a perfect match (i.e., $\Gamma_{in}(\omega) = 0$) at **one frequency** (i.e., the design frequency). However, if the signal frequency is **different** from this design frequency, then no match will occur (i.e., $\Gamma_{in}(\omega) \neq 0$).



Recall we discussed this
behavior **before**:

Freq. Response of a $\lambda/4$ Matching Network (contd.)

Q: But **why** is the result:

$$\Gamma_{in} = \Gamma + \frac{T^2 \Gamma_L e^{-j2\beta l}}{1 - \Gamma \Gamma_L}$$

or its approx form:

$$\Gamma_{in} = \Gamma + \Gamma_L e^{-j2\beta l}$$

dependent on **frequency**? I don't **see** frequency variable ω anywhere in these results!

A: Look **closer**!

- Remember that the value of spatial frequency β (in radians/meter) is dependent on the frequency ω of our eigen function (aka “the signal”):

$$\beta = \left(\frac{1}{v_p} \right) \omega$$

where you will recall that v_p is the propagation velocity of a wave moving along a transmission line.

- This velocity is a constant (i.e., $v_p = 1/\sqrt{LC}$), and so the spatial frequency β is directly proportional to the temporal frequency ω .
- Thus, we can rewrite:

$$\beta = \left(\frac{1}{v_p} \right) \omega$$

Where $T = l/v_p$ is the **time** required for the wave to **propagate** a distance l down a transmission line.

Freq. Response of a $\lambda/4$ Matching Network (contd.)

- As a result, we can write the input reflection coefficient as a function of **spatial frequency** β :
$$\Gamma_{in}(\beta) = \Gamma + \Gamma_L e^{-j2\beta l}$$
- Or equivalently as a function of **temporal frequency** ω :
$$\Gamma_{in}(\omega) = \Gamma + \Gamma_L e^{-j2\omega T}$$
- Frequently**, the reflection coefficient is simply written in terms of the **electrical length** θ of the transmission line, which is simply the **difference in relative phase** between the wave at the beginning and end of the length l of the TL.
$$\beta l = \theta = \omega T$$
- So that:
$$\Gamma_{in}(\theta) = \Gamma + \Gamma_L e^{-j2\theta}$$

Note we can simply insert the value $\theta = \beta l$ into this expression to get $\Gamma_{in}(\beta)$, or insert $\theta = \omega T$ into the expression to get $\Gamma_{in}(\omega)$.
- Now, we know that $\Gamma = \Gamma_L$ for a properly designed quarter-wave matching network, so the reflection coefficient function can be written as:
$$\Gamma_{in}(\theta) = \Gamma_L (1 + e^{-j2\theta})$$

Freq. Response of a $\lambda/4$ Matching Network (contd.)

• Note that: $1 = e^{j0} = e^{-j(\theta-\theta)} = e^{-j\theta} e^{+j\theta}$

• And that: $e^{-j2\theta} = e^{-j(\theta+\theta)} = e^{-j\theta} e^{-j\theta}$

• And so: $\Gamma_{in}(\theta) = \Gamma_L (1 + e^{-j2\theta})$

$$\Rightarrow \Gamma_L (e^{-j\theta} e^{+j\theta} + e^{-j\theta} e^{-j\theta})$$

$$= \Gamma_L e^{-j\theta} (e^{+j\theta} + e^{-j\theta})$$



$$= \Gamma_L e^{-j\theta} (2 \cos \theta)$$

• Now, **magnitude** of our result is:

$$|\Gamma_{in}(\theta)| = |\Gamma_L| |e^{-j\theta}| |2| |\cos \theta| = 2 |\Gamma_L| |\cos \theta|$$

• Note: $|\Gamma_{in}(\theta)|$ is **zero-valued** only when $\cos \theta = 0$. This of course occurs when $\theta = \pi/2$.

$$|\Gamma_{in}(\theta)|_{\theta=\pi/2} = 2 |\Gamma_L| \left| \cos \frac{\pi}{2} \right| = 0$$

Q: What the heck does this mean?

A: Remember, $\theta = \beta l$. Thus if $\theta = \pi/2$:

$$|\Gamma_{in}(\theta)|_{\theta=\pi/2} = 2 |\Gamma_L| \left| \cos \frac{\pi}{2} \right| = 0$$

As we (should have) suspected, the match occurs at the frequency whose wavelength is equal to **four times** the matching (Z_1) transmission line length, i.e. $\lambda = 4l$.

Freq. Response of a $\lambda/4$ Matching Network (contd.)

In other words, a perfect match occurs at the **frequency** where $l = \lambda/4$.

- Note the **physical** length l of the transmission line does **not** change with frequency, but the signal **wavelength** does:

$$\lambda = \frac{v_p}{f}$$

Q: So, at precisely what **frequency** does a quarter-wave transformer with length l provide a **perfect** match?

A: Recall that $\theta = \omega T$, where $T = l/v_p$. Thus, for $\theta = \pi/2$:

$$\theta = \frac{\pi}{2} = \omega T$$



$$\omega = \frac{\pi}{2} \frac{1}{T} = \frac{\pi}{2} \frac{v_p}{l}$$

- This frequency is called the **design frequency** of the matching network—it's the frequency where a **perfect** match occurs. We denote this as frequency ω_0 , which has wavelength λ_0 , i.e.:

$$\omega_0 = \frac{\pi}{2T} = \pi \frac{v_p}{2l}$$



$$\omega_0 = \frac{\pi}{2T} = \pi \frac{v_p}{2l}$$



$$\omega_0 = \frac{\pi}{2T} = \pi \frac{v_p}{2l}$$

Freq. Response of a $\lambda/4$ Matching Network (contd.)

- Given this, yet **another way** of expressing $\theta = \beta l$ is:

$$\theta = \beta l = \frac{\omega}{v_p} \left(\pi \frac{v_p}{2\omega_0} \right) = \pi \frac{\omega}{2\omega_0} = \pi \frac{f}{2f_0}$$

- Thus, we conclude:

$$|\Gamma_{in}(f)| = 2|\Gamma_L| \left| \cos \left(\pi \frac{f}{2f_0} \right) \right|$$

This expression helps in the determination (approximately) of the **bandwidth** of the quarter-wave transformer!

- First, we must **define** what we mean by bandwidth. Say the **maximum** acceptable level of the reflection coefficient is value Γ_m . This is an arbitrary value, set by **you** the microwave engineer (typical values of Γ_m range from 0.05 to 0.2).
- Let us denote the frequencies where this maximum value Γ_m occurs f_m . In other words:

$$|\Gamma_{in}(f = f_m)| = \Gamma_m = 2|\Gamma_L| \left| \cos \left(\pi \frac{f_m}{2f_0} \right) \right|$$

Freq. Response of a $\lambda/4$ Matching Network (contd.)

- There are **two solutions** to this equation, the first is:

$$f_{m1} = \frac{2f_0}{\pi} \cos^{-1} \left(\frac{\Gamma_m}{2|\Gamma_L|} \right)$$

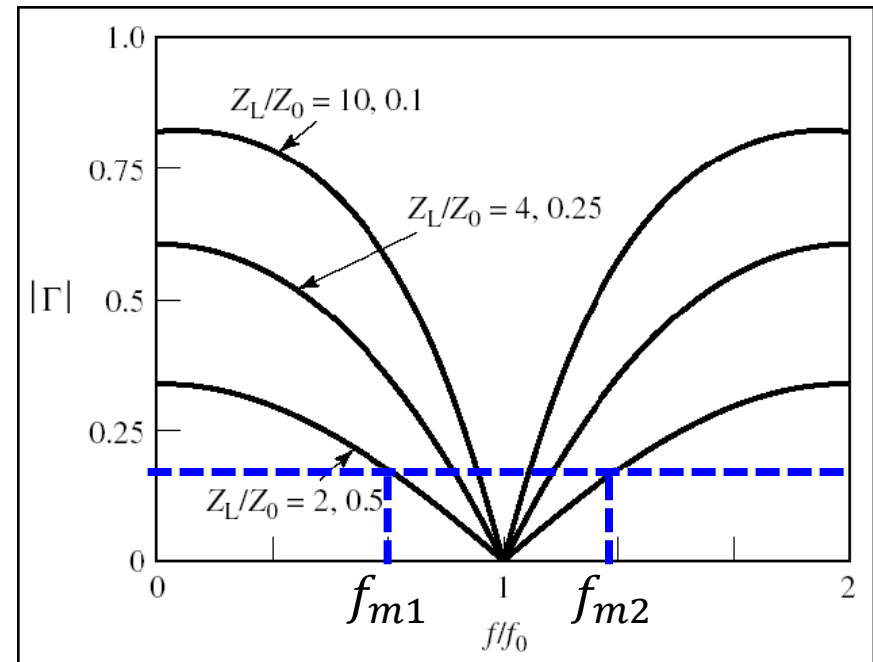
- And the second:

$$f_{m2} = \frac{2f_0}{\pi} \cos^{-1} \left(-\frac{\Gamma_m}{2|\Gamma_L|} \right)$$

Important note! Make sure $\cos^{-1}x$ is expressed in **radians**!

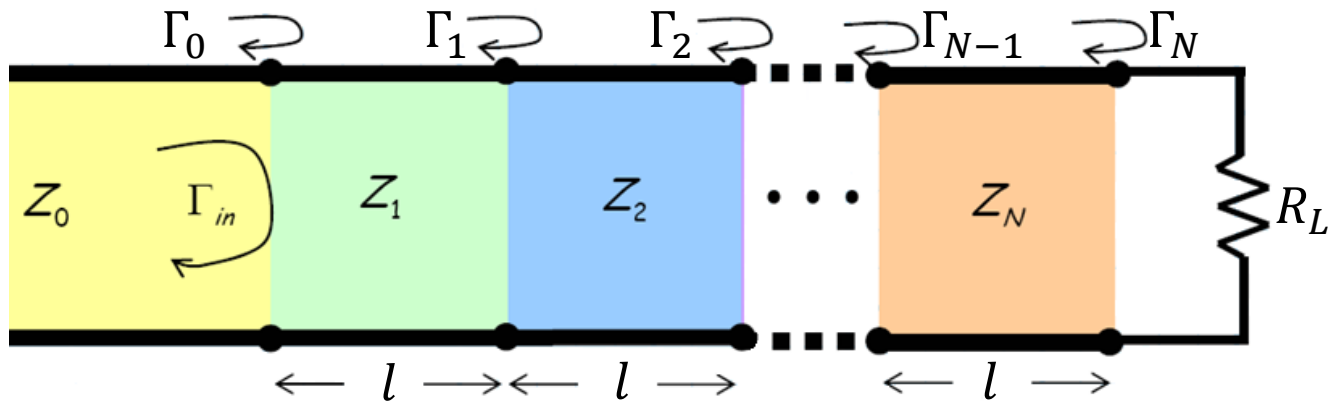
- You will find that $f_{m1} < f_0 < f_{m2}$. So the values f_{m1} and f_{m2} define the **lower** and **upper** limits on matching network **bandwidth**.

All this analysis was brought to you by the “**simple**” mathematical form of $\Gamma_{in}(f)$ that resulted from the theory of small reflections!



The Multi-section Transformer

- Consider a sequence of N transmission line **sections**; each section has **equal length** l , but **dissimilar** characteristic impedances:



- Where the marginal reflection coefficients are: $\Gamma_0 \doteq \frac{Z_1 - Z_0}{Z_1 + Z_0}$ $\Gamma_n \doteq \frac{Z_{n+1} - Z_n}{Z_{n+1} + Z_n}$ $\Gamma_N \doteq \frac{Z_L - Z_N}{Z_L + Z_N}$
- If the load resistance R_L is **less** than Z_0 , then we should design the transformer such that: $Z_0 > Z_1 > Z_2 > Z_3 > \dots > Z_N > R_L$
- Conversely, if R_L is **greater** than Z_0 , then we will design the transformer such that: $Z_0 < Z_1 < Z_2 < Z_3 < \dots < Z_N < R_L$

The Multi-section Transformer (contd.)

In other words, we **gradually transition** from Z_0 to R_L !

Note that since R_L is **real**, and since we assume **lossless** transmission lines, all Γ_n will be **real** (this is important!).

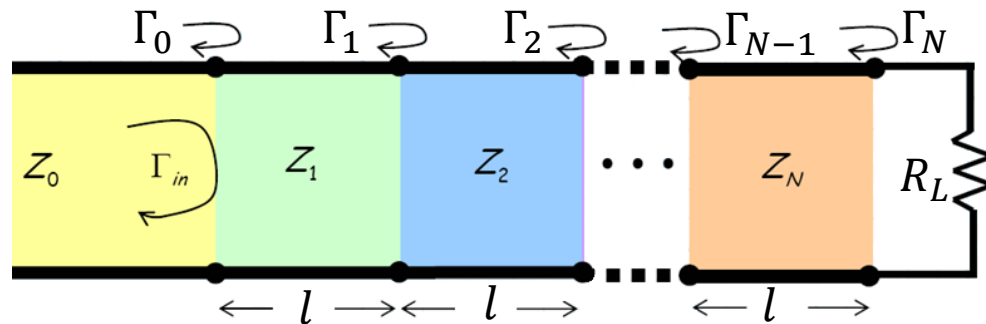
- Likewise, since we **gradually** transition from one section to another, each value:

$$Z_{n+1} - Z_n \quad \text{will be small.}$$

- As a result, each marginal reflection coefficient Γ_n will be **real** and have a **small** magnitude.

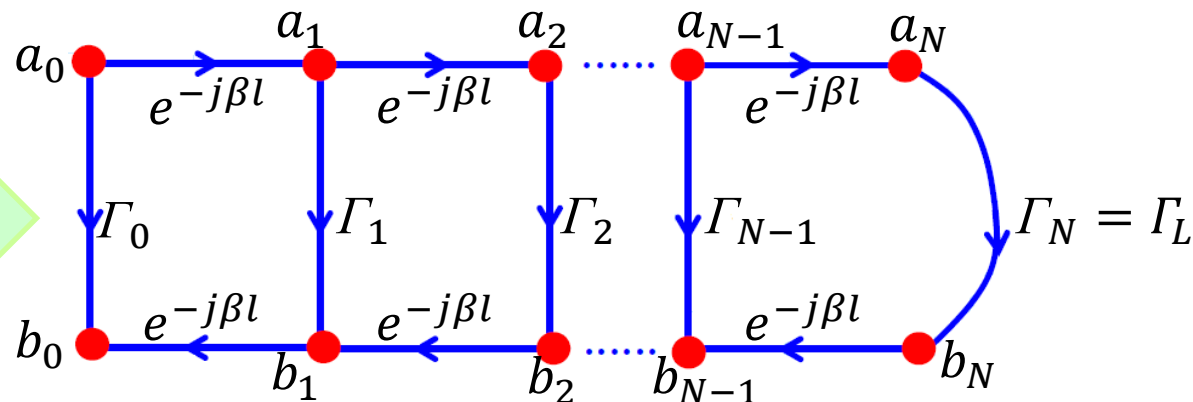
This is also **important**, as it means that we can apply the “**theory of small reflections**” to analyse this multi-section transformer!

- The theory of small reflections allows us to **approximate** the input reflection coefficient of the transformer as:

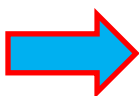


The Multi-section Transformer (contd.)

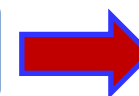
The approximate SFG when
applying the theory of small
reflections!



$$\frac{b_0}{a_0} = \Gamma_{in}(\beta)$$



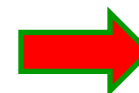
$$\approx \Gamma_0 + \Gamma_1 e^{-j2\beta l} + \Gamma_2 e^{-j4\beta l} + \dots + \Gamma_N e^{-j2N\beta l}$$



$$= \sum_{n=0}^N \Gamma_n e^{-j2n\beta l}$$

- We can alternatively express the input reflection coefficient as a function of **frequency** ($\beta l = \omega T$):

$$\Gamma_{in}(\omega) = \Gamma_0 + \Gamma_1 e^{-j2\omega T} + \Gamma_2 e^{-j4\omega T} + \dots + \Gamma_N e^{-j2N\omega T}$$



$$= \sum_{n=0}^N \Gamma_n e^{-j(2nT)\omega}$$

where: $T = \frac{l}{v_p} \leftarrow \text{propagation time through 1 section}$

The Multi-section Transformer (contd.)

- We see that the function $\Gamma_{in}(\omega)$ is expressed as a **weighted** set of **N basis functions!** i.e.,

The diagram illustrates the synthesis of the input reflection coefficient $\Gamma_{in}(\omega)$ as a weighted sum of basis functions. It features three main components: a central equation box, a coefficient definition box, and a basis function definition box. The central box, outlined in blue, contains the equation $\Gamma_{in}(\omega) = \sum_{n=0}^N c_n \Psi(\omega)$. To its left, a yellow box contains the definition $c_n = \Gamma_n$, with a red curved arrow pointing from it to the coefficient c_n in the central equation. To the right, a green box contains the definition $\Psi(\omega) = e^{-j(2nT)\omega}$, with a green curved arrow pointing from it to the basis function $\Psi(\omega)$ in the central equation.

$$\Gamma_{in}(\omega) = \sum_{n=0}^N c_n \Psi(\omega)$$
$$c_n = \Gamma_n$$
$$\Psi(\omega) = e^{-j(2nT)\omega}$$

- We find, therefore, that by **selecting** the proper values of basis weights c_n (i.e., the proper values of reflection coefficients Γ_n), we can **synthesize** any function $\Gamma_{in}(\omega)$ of frequency ω , provided that:
 - $\Gamma_{in}(\omega)$ is **periodic** in $\omega = 1/2T$.
 - we have sufficient **number** of sections N .

Q: What function **should** we synthesize?

A: Ideally, we would want to make $\Gamma_{in}(\omega) = 0$ (i.e., the reflection coefficient is zero for all frequencies).

Bad News: this **ideal** function $\Gamma_{in}(\omega) = 0$ would require an **infinite** number of sections (i.e., $N = \infty$)!

The Multi-section Transformer (contd.)

Therefore, we seek to find an “**optimal**” function for $\Gamma_{in}(\omega)$, given a **finite** number of N elements.

Once we determine these optimal functions, we can find the values of coefficients Γ_n (or equivalently, Z_n) that will result in a matching transformer that exhibits this **optimal** frequency response.

- To **simplify** this process, we can make the transformer **symmetrical**, such that:

$$\Gamma_0 = \Gamma_N, \quad \Gamma_1 = \Gamma_{N-1}, \quad \Gamma_2 = \Gamma_{N-2}, \quad \dots \dots$$



Note: this **does NOT** mean that:

$$Z_0 = Z_N, \quad Z_1 = Z_{N-1}, \quad Z_2 = Z_{N-2}, \quad \dots \dots$$

The Multi-section Transformer (contd.)

- We then find that:

$$\Gamma(\omega) = e^{-jN\omega T} \left[\Gamma_0(e^{jN\omega T} + e^{-jN\omega T}) + \Gamma_1(e^{j(N-2)\omega T} + e^{-j(N-2)\omega T}) + \Gamma_2(e^{j(N-4)\omega T} + e^{-j(N-4)\omega T}) + \dots \right]$$

- and since: $e^{jx} + e^{-jx} = 2\cos(x)$

- we can write for N **even**:

$$\Gamma(\omega) = 2e^{-jN\omega T} \left[\Gamma_0 \cos N\omega T + \Gamma_1 \cos(N-2)\omega T + \dots + \Gamma_n \cos(N-2n)\omega T + \dots + \frac{1}{2} \Gamma_{N/2} \right]$$

- whereas for N **odd**:

$$\Gamma(\omega) = 2e^{-jN\omega T} \left[\Gamma_0 \cos N\omega T + \Gamma_1 \cos(N-2)\omega T + \dots + \Gamma_n \cos(N-2n)\omega T + \dots + \Gamma_{(N-1)/2} \cos \omega T \right]$$

The remaining **question** then is this: given an optimal and realizable function $\Gamma_{in}(\omega)$, **how** do we determine the necessary number of **sections** N, and **how** do we determine the **values** of all reflection coefficients Γ_n ??

The Multi-section Transformer (contd.)

Multi-section transformer is often used to maximize the bandwidth of transformer.

Alternatively, we can say that one way to **maximize bandwidth** is to construct a multi-section matching network with a function $\Gamma(f)$ that is either **maximally flat** or can be considered flat **albeit with pass-band ripple**.

Binomial Function satisfies the condition of maximum flatness

Chebyshev Polynomial can be considered flat **with pass-band ripple**

Maximally Flat Functions

- Consider some function $f(x)$. Say that we know the value of the function at $x = 1$ is 5:

$$f(x=1) = 5$$



This of course says **something** about the function $f(x)$, but it **doesn't** tell us much!

- We can additionally determine the **first derivative** of this function, and likewise evaluate this derivative **at** $x = 1$. Say that this value turns out to be **zero**:

$$\left. \frac{df(x)}{dx} \right|_{x=1} = 0$$



Note that this does not mean that the derivative of $f(x)$ is equal to zero, it merely means that the derivative of $f(x)$ is zero **at the value** $x = 1$. Presumably, $\frac{df(x)}{dx}$ is **non-zero** at **other** values of x .

So, we now have **two** pieces of information about the function $f(x)$. We can add to this list by continuing to take higher order derivatives and evaluating them at the single point $x = 1$.

Maximally Flat Functions (contd.)

- Let's say that the values of **all** the derivatives (at $x = 1$) turn out to have a zero value:

$$\left. \frac{df^n(x)}{dx^n} \right|_{x=1} = 0 \quad \text{for } n = 1, 2, 3, \dots, \infty$$

We say that this function is **completely flat** at the point $x = 1$. Because **all** the derivatives are zero at $x = 1$, it means that the function cannot change in value from that at $x = 1$.

In other words, if the function has a value of 5 at $x = 1$, (i.e., $f(x = 1) = 5$), then the function **must** have a value of 5 at **all** x !



The function $f(x)$ thus must be the **constant** function: $f(x) = 5$.

Maximally Flat Functions (contd.)

- Now let's consider the following **problem**—say some function $f(x)$ has the following form:

$$f(x) = ax^3 + bx^2 + cx$$

- We wish to **determine** the values a , b , and c so that:
 - $f(x=1) = 5$
 - and that the value of the function $f(x)$ is as **close** to a value of 5 as possible in the region where $x = 1$.
 - In other words, we want the function to have the value of 5 at $x = 1$, and to **change** from that value as **slowly** as possible as we “move” from $x = 1$.

Q: Don't we simply want the **completely** flat function $f(x) = 5$?

A: That would be the **ideal** function for this case, but notice that solution is **not** an option. Note there are **no** values of a , b , and c that will make: $ax^3 + bx^2 + cx = 5$ for **all** values x .

Maximally Flat Functions (contd.)

Q: So what do we do?

A: Instead of the completely flat solution, we can find the **maximally flat** solution!

The **maximally flat** solution comes from determining the values a , b , and c so that as many derivatives **as possible** are **zero** at the point $x = 1$.

- For example, we wish to make the **first derivate** equal to zero at $x = 1$:

$$0 = \left. \frac{df(x)}{dx} \right|_{x=1} \xrightarrow{\text{red arrow}} 0 = (3ax^2 + 2bx + c) \Big|_{x=1} \xrightarrow{\text{orange arrow}} 3a + 2b + c = 0$$

- Similarly, we wish to make the **second derivative** equal to zero at $x = 1$:

$$0 = \left. \frac{d^2f(x)}{dx^2} \right|_{x=1} \xrightarrow{\text{yellow arrow}} 0 = (6ax + 2b) \Big|_{x=1} \xrightarrow{\text{blue arrow}} 6a + 2b = 0$$

Here we must **stop** taking derivatives, as our solution only has **three degrees of design freedom** (i.e., 3 unknowns a , b , and c).

Maximally Flat Functions (contd.)

Q: But we only have taken **two** derivatives, can't we take **one more**?

A: No! We already have a **third** “design” equation: the value of the function **must** be 5 at $x = 1$:

$$5 = f(x=1) = a + b + c$$

- So, we have used the **maximally flat** criterion at $x = 1$ to generate **three** equations and **three** unknowns:

$$3a + 2b + c = 0$$

$$6a + 2b = 0$$

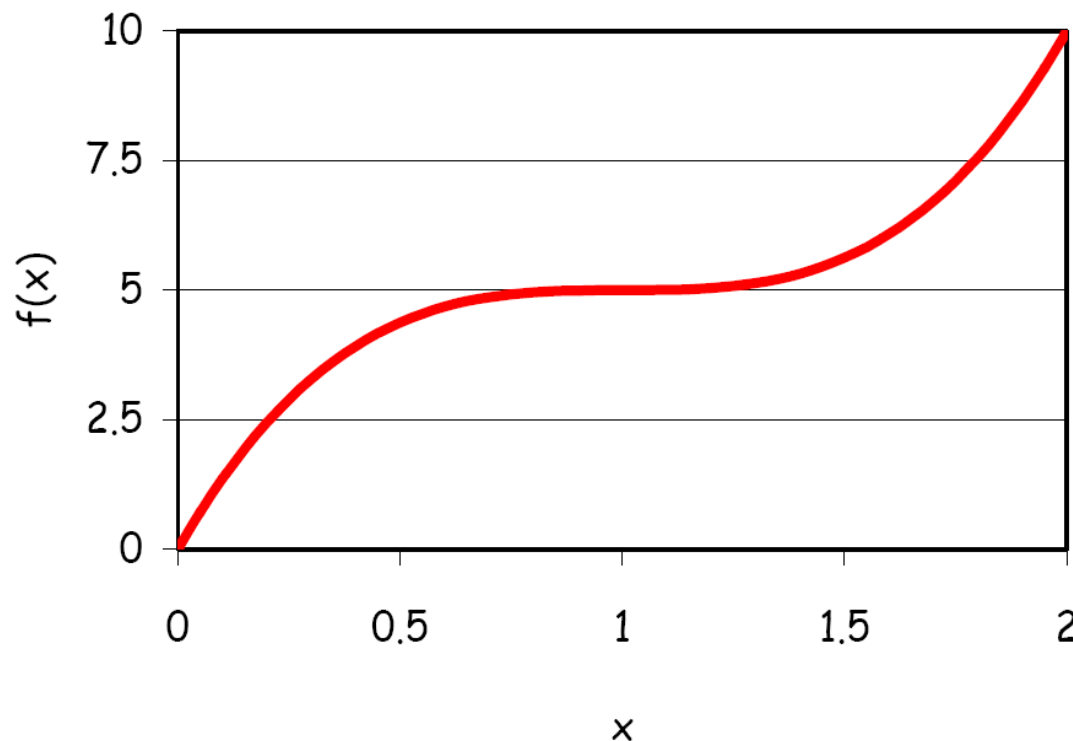
$$a + b + c = 5$$

- Solving, we find: $a = 5,$ $b = -15,$ $c = 15$

Maximally Flat Functions (contd.)

- Therefore, the maximally flat function (at $x = 1$) is:

$$f(x) = 5x^3 - 15x^2 + 15x$$



The Binomial Multi-Section Transformer

- Recall that a **multi-section matching network** can be described using the theory of small reflections as:

$$\Gamma_{in}(\omega) = \Gamma_0 + \Gamma_1 e^{-j2\omega T} + \Gamma_2 e^{-j4\omega T} + \dots + \Gamma_N e^{-j2N\omega T} \quad \Rightarrow \quad = \sum_{n=0}^N \Gamma_n e^{-j(2nT)\omega}$$

where: $T = \frac{l}{v_p} \leftarrow \text{propagation time through 1 section}$

Note that for a multi-section transformer, we have **N degrees of design freedom**, corresponding to the N characteristic impedance values Z_n .

Q: What should the values of Γ_n (i.e., Z_n) be?

A: We need to define N independent **design equations**, which we can then use to solve for the N values of **characteristic impedance** Z_n .

The Binomial Multi-Section Transformer (contd.)

- First, we start with a single **design frequency** ω_0 , where we wish to achieve a **perfect** match:

$$\Gamma_{in}(\omega = \omega_0) = 0$$



That's just **one** design equation: we need **N - 1** more!

- These addition equations can be selected using **many** criteria—one such criterion is to make the function $\Gamma_{in}(\omega)$ **maximally flat** at the point $\omega = \omega_0$.
- To accomplish this, we first consider the **Binomial Function**:

$$\Gamma(\theta) = A(1 + e^{-j2\theta})^N$$
- This function has the desirable **properties** that:

$$\Gamma\left(\theta = \frac{\pi}{2}\right) = A(1 + e^{-j\pi})^N = A(1 - 1)^N = 0$$

- and that:

$$\left. \frac{d^n \Gamma(\theta)}{d\theta^n} \right|_{\theta=\pi/2} = 0 \quad \text{for } n = 1, 2, 3, \dots, N - 1$$

The Binomial Multi-Section Transformer (contd.)

$$\Gamma(\theta) = A(1 + e^{-j2\theta})^N$$



In other words, this Binomial Function is **maximally flat** at the point $\theta = \pi/2$, where it has a value of $\Gamma(\theta = \pi/2) = 0$.

Q: So? What does **this** have to do with our multi-section matching network?

A: Let's **expand** (multiply out the N identical product terms) of the Binomial Function:

$$\Gamma(\theta) = A(1 + e^{-j2\theta})^N \longrightarrow = A(C_0^N + C_1^N e^{-j2\theta} + C_2^N e^{-j4\theta} + C_3^N e^{-j6\theta} + \dots + C_N^N e^{-j2N\theta})$$

where: $C_n^N \doteq \frac{N!}{(N-n)!n!}$

- Compare this to an **N-section** transformer function:

$$\Gamma_{in}(\omega) = \Gamma_0 + \Gamma_1 e^{-j2\omega T} + \Gamma_2 e^{-j4\omega T} + \dots + \Gamma_N e^{-j2N\omega T}$$

- it is obvious the two functions have **identical** forms, **provided** that:

$$\Gamma_n = AC_n^N \quad \omega T = \theta$$

The Binomial Multi-Section Transformer (contd.)

Moreover, we find that this function is very **desirable** from the standpoint of the a matching network. Recall that $\Gamma(\theta) = 0$ at $\theta = \pi/2$ — a **perfect** match!

Additionally, the function is **maximally flat** at $\theta = \pi/2$, therefore $\Gamma(\theta) \approx 0$ over a wide range around $\theta = \pi/2$ — a **wide bandwidth**!

Q: But how does $\theta = \pi/2$ relate to frequency ω ?

A: Remember that $\omega T = \theta$, so the value $\theta = \pi/2$ corresponds to the frequency:

$$\omega_0 = \frac{1}{T} \frac{\pi}{2} = \frac{v_p}{l} \frac{\pi}{2}$$

This frequency (ω_0) is therefore our **design** frequency—the frequency where we have a **perfect** match.

- Note that the length l has an interesting **relationship** with this frequency:

$$l = \frac{v_p}{\omega_0} \frac{\pi}{2} = \frac{1}{\beta_0} \frac{\pi}{2} = \frac{\lambda_0}{2\pi} \frac{\pi}{2} = \frac{\lambda_0}{4}$$

The Binomial Multi-Section Transformer (contd.)

- In other words, a **Binomial** Multi-section matching network will have a **perfect** match at the frequency where the section lengths l are a **quarter wavelength**!

Thus, we have our first design rule:

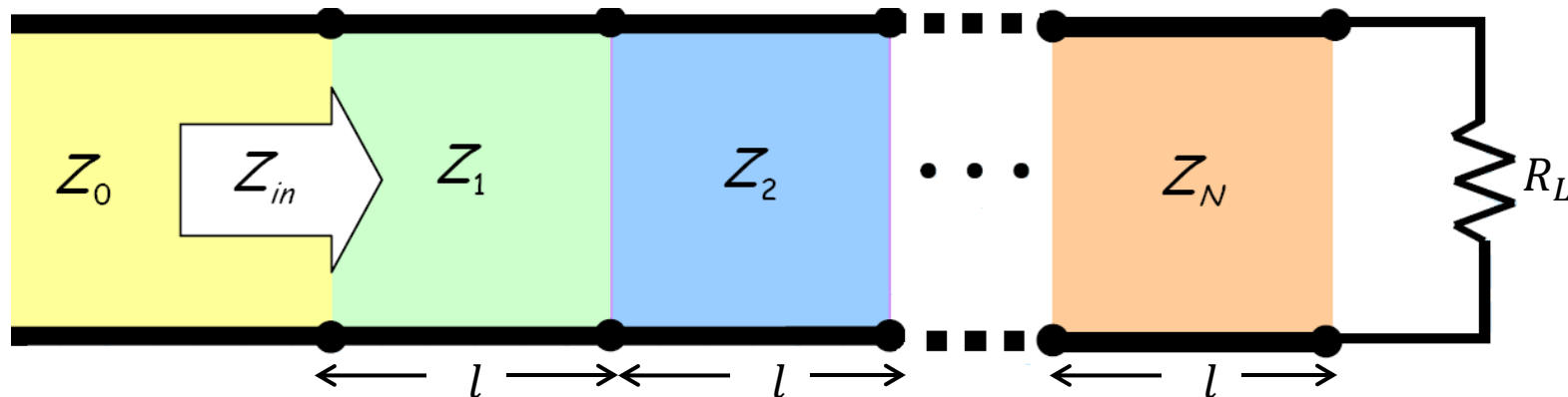
Set section lengths l so that they are a **quarter-wavelength** $(\lambda_0/4)$ at the design frequency ω_0 .

Q: I see! And then we select all the values Z_n such that $\Gamma_n = AC_n^N$. But wait! **What** is the value of **A** ??

A: We can determine this value by evaluating a **boundary condition**!

The Binomial Multi-Section Transformer (contd.)

- Specifically, we can **easily** determine the value of $\Gamma(\omega)$ at $\omega = 0$.



- Note as ω approaches **zero**, the electrical length βl of each section will **likewise** approach zero. Thus, the input impedance Z_{in} will simply be equal to R_L as $\omega \rightarrow 0$.
- As a result, the input reflection coefficient $\Gamma(\omega = 0)$ **must** be:

$$\Gamma(\omega = 0) = \frac{Z_{in}(\omega = 0) - Z_0}{Z_{in}(\omega = 0) + Z_0} = \frac{R_L - Z_0}{R_L + Z_0}$$

- However, we **likewise** know that:

$$\Gamma(0) = A(1 + e^{-j2(0)})^N = A(1 + 1)^N = A2^N$$

The Binomial Multi-Section Transformer (contd.)

- Equating the two expressions:

$$A2^N = \frac{R_L - Z_0}{R_L + Z_0}$$

- therefore:

$$A = 2^{-N} \frac{R_L - Z_0}{R_L + Z_0}$$



(A can be negative!)

- We now have a formulation to calculate the **required marginal reflection coefficients** Γ_n :

$$\Gamma_n = AC_n^N = \frac{AN!}{(N-n)!n!} = 2^{-N} \frac{R_L - Z_0}{R_L + Z_0} \frac{N!}{(N-n)!n!}$$

we **also** know that these marginal reflection coefficients are physically related to the characteristic impedances of each section as:

$$\Gamma_n = \frac{Z_{n+1} - Z_n}{Z_{n+1} + Z_n}$$

- Equating the two and solving, we find that that the section characteristic impedances must satisfy:

$$\Gamma_n = AC_n^N = \frac{AN!}{(N-n)!n!} = 2^{-N} \frac{R_L - Z_0}{R_L + Z_0} \frac{N!}{(N-n)!n!}$$

The Binomial Multi-Section Transformer (contd.)

Note this is an **iterative** procedure—we determine Z_1 from Z_0 , Z_2 from Z_1 , and so forth.

Q: This result **appears** to be our second design equation.

A: Alas, there is a **big problem** with this result.

- Note that there are $N+1$ coefficients Γ_n (i.e., $n \in \{0, 1, \dots, N\}$) in the Binomial series, yet there are only N design degrees of freedom (i.e., there are only N transmission line sections!).
- Thus, our design is a bit **over constrained**, a result that manifests itself the finally marginal reflection coefficient Γ_N .

- Note from this iterative solution, the **last** transmission line impedance Z_N is selected to satisfy the **mathematical** requirement of the **penultimate** reflection coefficient Γ_{N-1} .

$$\Gamma_{N-1} = \frac{Z_N - Z_{N-1}}{Z_N + Z_{N-1}} = AC_{N-1}^N$$

The Binomial Multi-Section Transformer (contd.)

- Therefore the last impedance must be:
$$Z_N = Z_{N-1} \frac{1 + AC_{N-1}^N}{1 - AC_{N-1}^N}$$

- But there is **one more** mathematical requirement!
The last marginal reflection coefficient **must** likewise satisfy:

$$\Gamma_N = AC_N^N = 2^{-N} \frac{R_L - Z_0}{R_L + Z_0}$$

where we use the fact that $C_N^N = 1$.

But, we **selected** Z_N to satisfy the requirement for Γ_{N-1} ,—we have no **physical** design parameter to satisfy this last **mathematical** requirement for Γ_N !

- As a result, we find to our great consternation that the last requirement is not satisfied:

$$\Gamma_N = \frac{R_L - Z_N}{R_L + Z_N} \neq AC_N^N$$

The Binomial Multi-Section Transformer (contd.)

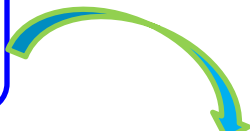
Q: Yikes! Does this mean that the resulting matching network will **not** have the desired Binomial frequency response?

A: That's **exactly** what it means!

Q: You big #%@#\$%&!!!! **Why** did you **waste** all my time discussing an over-constrained design problem that can't be built?

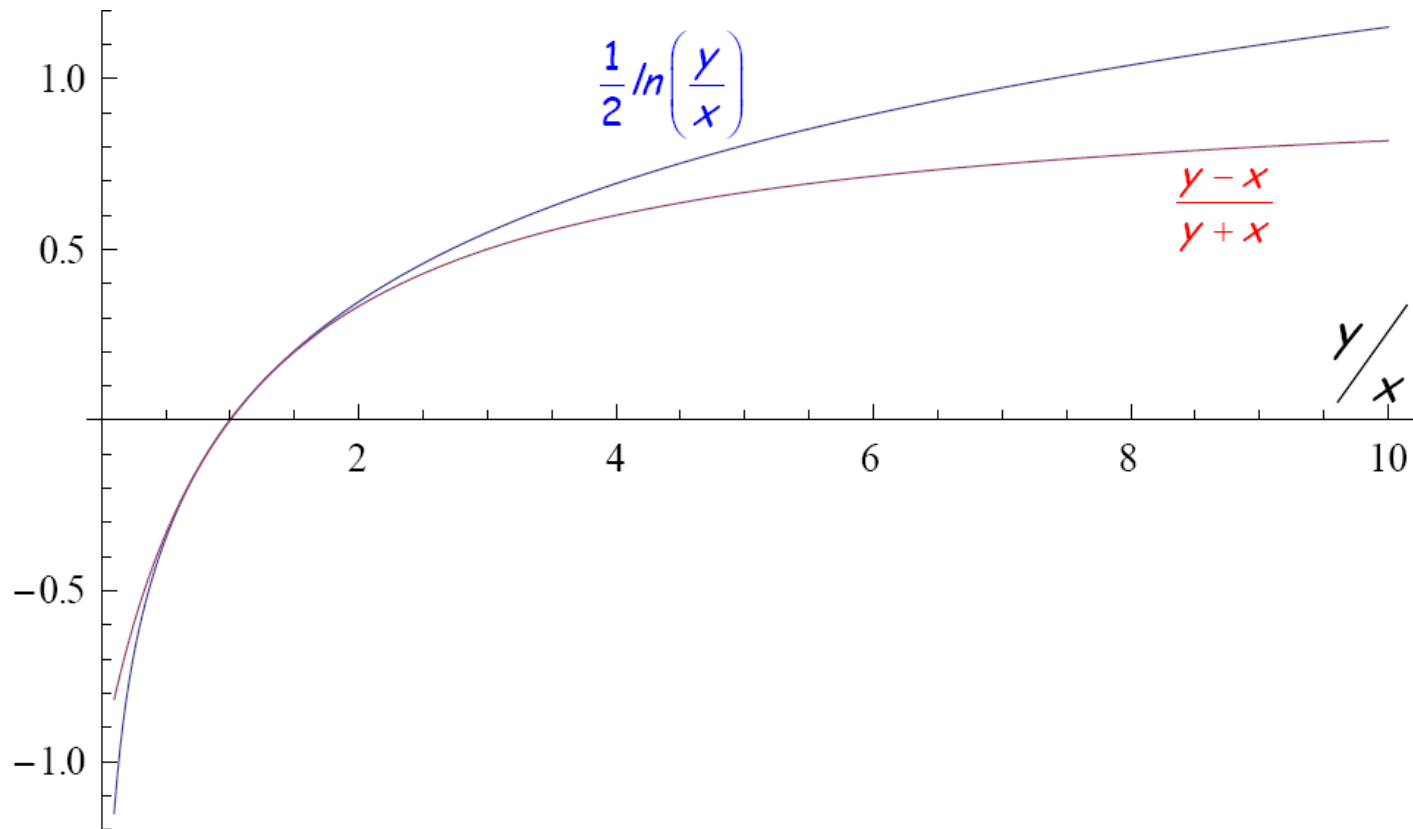
A: Relax; there is a **solution** to our dilemma—albeit an **approximate** one.

- **You** undoubtedly have previously used the **approximation**:

$$\frac{y-x}{y+x} \approx \frac{1}{2} \ln \left(\frac{y}{x} \right)$$


This approximation is especially **accurate** when $y-x$ is small (i.e., when $y/x \approx 1$).

The Binomial Multi-Section Transformer (contd.)



The Binomial Multi-Section Transformer (contd.)

- Now, we know that the values of Z_{n+1} and Z_n in a multi-section matching network are typically **very close**, such that $|Z_{n+1} - Z_n|$ is small.
- Thus, we use the approximation:

$$\Gamma_n = \frac{Z_{n+1} - Z_n}{Z_{n+1} + Z_n} \approx \frac{1}{2} \ln \left(\frac{Z_{n+1}}{Z_n} \right)$$

- Likewise, we can **also** apply this approximation (although not as accurately) to the value of A:

$$A = 2^{-N} \frac{R_L - Z_0}{R_L + Z_0} \approx 2^{-(N+1)} \ln \left(\frac{R_L}{Z_0} \right)$$

- So, let's **start over**, only this time we'll use these **approximations**. First, determine A:

$$A \approx 2^{-(N+1)} \ln \left(\frac{R_L}{Z_0} \right) \quad (\text{A can be negative!})$$



- Now use this result to calculate the **mathematically required** marginal reflection coefficients Γ_n :

$$\Gamma_n = A C_n^N = \frac{AN!}{(N-n)!n!}$$

The Binomial Multi-Section Transformer (contd.)

- Of course, we **also** know that these marginal reflection coefficients are physically related to the characteristic impedances of each section as:
- Equating the two and solving, we find that that the section characteristic impedances **must** satisfy:

$$\Gamma_n \approx \frac{1}{2} \ln \left(\frac{Z_{n+1}}{Z_n} \right)$$

$$Z_{n+1} = Z_n \exp[2\Gamma_n]$$

This is our second design rule. Note it is an **iterative** rule—we determine Z_1 from Z_0 , Z_2 from Z_1 , and so forth.

Q: Huh? How is this any better? How does applying **approximate** math lead to a **better** design result??

A: Applying these approximations help resolve our over constrained problem. Recall that the over-constraint resulted in:

$$\Gamma_N = \frac{R_L - Z_N}{R_L + Z_N} \neq AC_N^N$$

The Binomial Multi-Section Transformer (contd.)

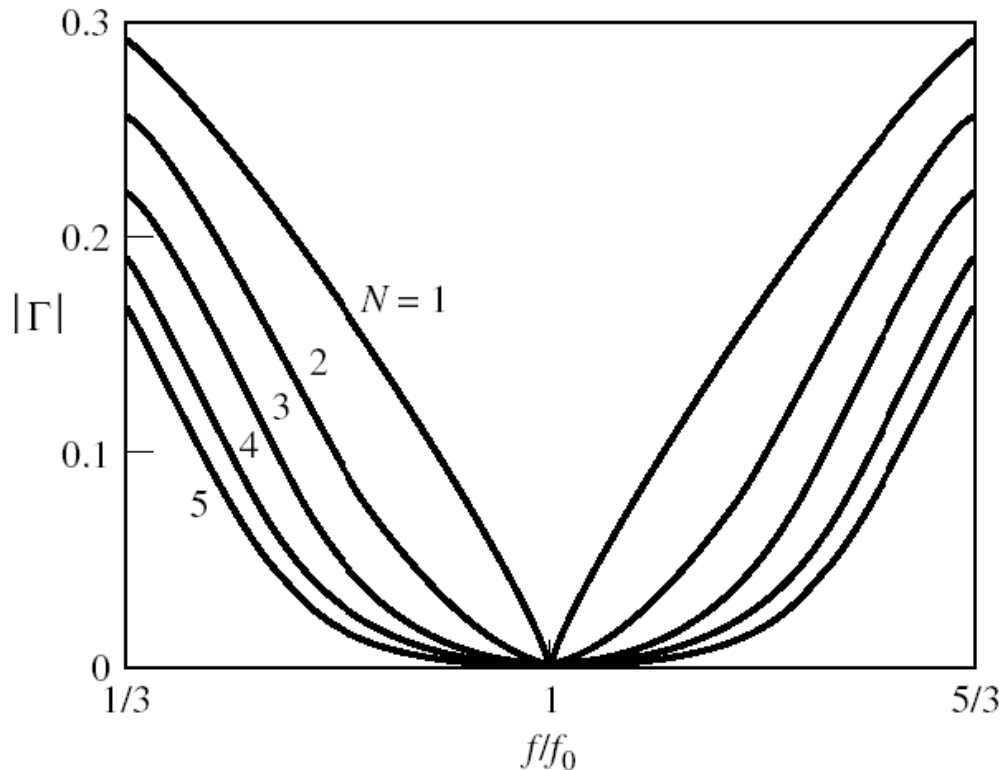
- But, as it turns out, the approximations leads to the happy situation where:

$$\Gamma_N \approx \frac{1}{2} \ln \left(\frac{R_L}{Z_N} \right) = AC_N^N \quad \leftarrow \text{provided that the value } A \text{ is the approximation as well.}$$

- Effectively, these approximations couple the results, such that each value of characteristic impedance Z_n **approximately** satisfies both Γ_n and Γ_{n+1} .
Summarizing:

- If you use the “**exact**” design equations to determine the characteristic impedances Z_n , the last value Γ_n will exhibit a significant numeric error, and your design **will not** appear to be maximally flat.
- If you instead use the “**approximate**” design equations to determine the characteristic impedances Z_n , all values Γ_n will exhibit a slight error, but the resulting design **will** appear to be **maximally flat**, **Binomial** reflection coefficient function $\Gamma(\omega)$!

The Binomial Multi-Section Transformer (contd.)



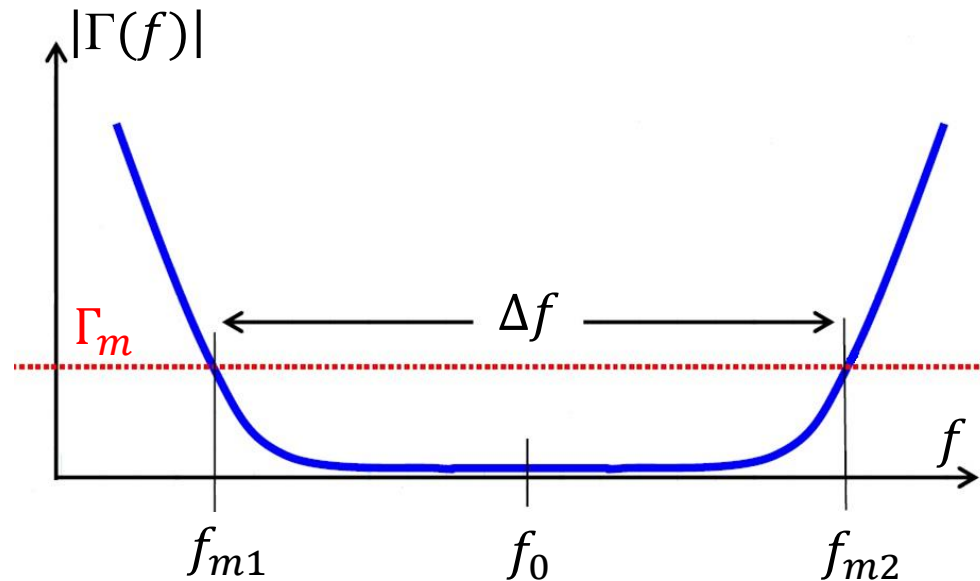
Note that as we **increase** the number of **sections**, the matching **bandwidth** increases.

Q: Can we determine the **value** of this bandwidth?

A: Sure! But we first must **define** what we mean by bandwidth.

The Binomial Multi-Section Transformer (contd.)

- As we move from the design (perfect match) frequency f_0 the value $|\Gamma(f)|$ will **increase**. At some frequency (say, f_m) the magnitude of the reflection coefficient will increase to some **unacceptably** high value (say, Γ_m). At that point, we **no longer** consider the device to be matched.
- Note there are **two** values of frequency f_m —one value **less** than design frequency f_0 , and one value **greater** than design frequency f_0 . These two values define the **bandwidth** Δf of the matching network:



$$\Delta f = f_{m2} - f_{m1} = 2(f_0 - f_{m1}) = 2(f_{m2} - f_0)$$

The Binomial Multi-Section Transformer (contd.)

Q: So what is the **numerical** value of Γ_m ?

A: I don't know—it's up to **you** to decide!

Every engineer must determine what **they** consider to be an acceptable match (i.e., decide Γ_m). This decision depends on the **application** involved, and the **specifications** of the overall microwave system being designed.

However, we **typically** set Γ_m to be 0.2 or less.

Q: OK, after we have selected Γ_m , can we determine the **two** frequencies f_m ?

A: Sure! We just have to do a little **algebra**.

- We start by **rewriting** the Binomial function:

$$\Gamma(\theta) = A(1 + e^{-j2\theta})^N \quad \Rightarrow \quad = Ae^{-jN\theta} (e^{+j\theta} + e^{-j\theta})^N \quad \Rightarrow \quad = Ae^{-jN\theta} (2\cos\theta)^N$$

- Now, we take the **magnitude** of this function:

$$|\Gamma(\theta)| = 2^N |A| |e^{-jN\theta}| |\cos\theta|^N \quad \Rightarrow \quad |\Gamma(\theta)| = 2^N |A| |\cos\theta|^N$$

The Binomial Multi-Section Transformer (contd.)

- Now, we **define** the values θ where $|\Gamma(\theta)| = \Gamma_m$ as θ_m . i.e., :

$$\Gamma_m = |\Gamma(\theta = \theta_m)| = 2^N |A| |\cos \theta_m|^N$$

- We can now solve for θ_m (in **radians!**) in terms of Γ_m :

$$\theta_{m1} = \cos^{-1} \left[\frac{1}{2} \left(\frac{\Gamma_m}{|A|} \right)^{1/N} \right]$$

$$\theta_{m2} = \cos^{-1} \left[-\frac{1}{2} \left(\frac{\Gamma_m}{|A|} \right)^{1/N} \right]$$

Note that there are **two solutions** to the above equation (one **less** than $\pi/2$ and one **greater** than $\pi/2$)!

- Now, we can convert the values of θ_m into specific frequencies.
- Recall that $\omega T = \theta$, therefore:

$$\omega_m = \frac{1}{T} \theta_m = \frac{v_p}{l} \theta_m$$

The Binomial Multi-Section Transformer (contd.)

- But recall also that $l = \lambda_0/4$, where λ_0 is the wavelength at the **design frequency** f_0 (not f_m !), and where $\lambda_0 = v_p/f_0$.
- Thus we can conclude:

$$\omega_m = \frac{v_p}{l} \theta_m = \frac{4v_p}{\lambda_0} \theta_m = (4f_0) \theta_m$$



$$f_m = \frac{\omega_m}{2\pi} = \frac{(2f_0)\theta_m}{\pi}$$

where θ_m is
expressed in
radians.

- Therefore:

$$f_{m1} = \frac{2f_0}{\pi} \cos^{-1} \left[\frac{1}{2} \left(\frac{\Gamma_m}{|A|} \right)^{1/N} \right]$$

$$f_{m2} = \frac{2f_0}{\pi} \cos^{-1} \left[-\frac{1}{2} \left(\frac{\Gamma_m}{|A|} \right)^{1/N} \right]$$

- Thus, the **bandwidth** of the binomial matching network can be determined as:

$$\Delta f = 2(f_0 - f_{m1}) = 2f_0 - \frac{4f_0}{\pi} \cos^{-1} \left[\frac{1}{2} \left(\frac{\Gamma_m}{|A|} \right)^{1/N} \right]$$

Note that this equation can be used to determine the **bandwidth** of a binomial matching network, given Γ_m and number of sections N .

The Binomial Multi-Section Transformer (contd.)

$$\Delta f = 2(f_0 - f_{m1}) = 2f_0 - \frac{4f_0}{\pi} \cos^{-1} \left[\frac{1}{2} \left(\frac{\Gamma_m}{|A|} \right)^{1/N} \right]$$

It can also be used to determine the **number of sections N** required to meet a specific bandwidth requirement!

- Finally, we can list the **design steps** for a binomial matching network:
 - Determine** the value N required to meet the bandwidth (Δf and Γ_m) requirements.
 - Determine the **approximate** value A from Z_0 , R_L and N.
 - Determine the **marginal reflection coefficients** $\Gamma_n = AC_n^N$ required by the **binomial** function.
 - Determine the characteristic impedance of each section using the **iterative approximation**: $Z_{n+1} = Z_n \exp[2\Gamma_n]$.
 - Perform the **sanity check**: $\Gamma_N \approx \frac{1}{2} \ln \left(\frac{R_L}{Z_N} \right) = AC_n^N$.
 - Determine section **length** $l = \lambda_0/4$ for design frequency f_0 .

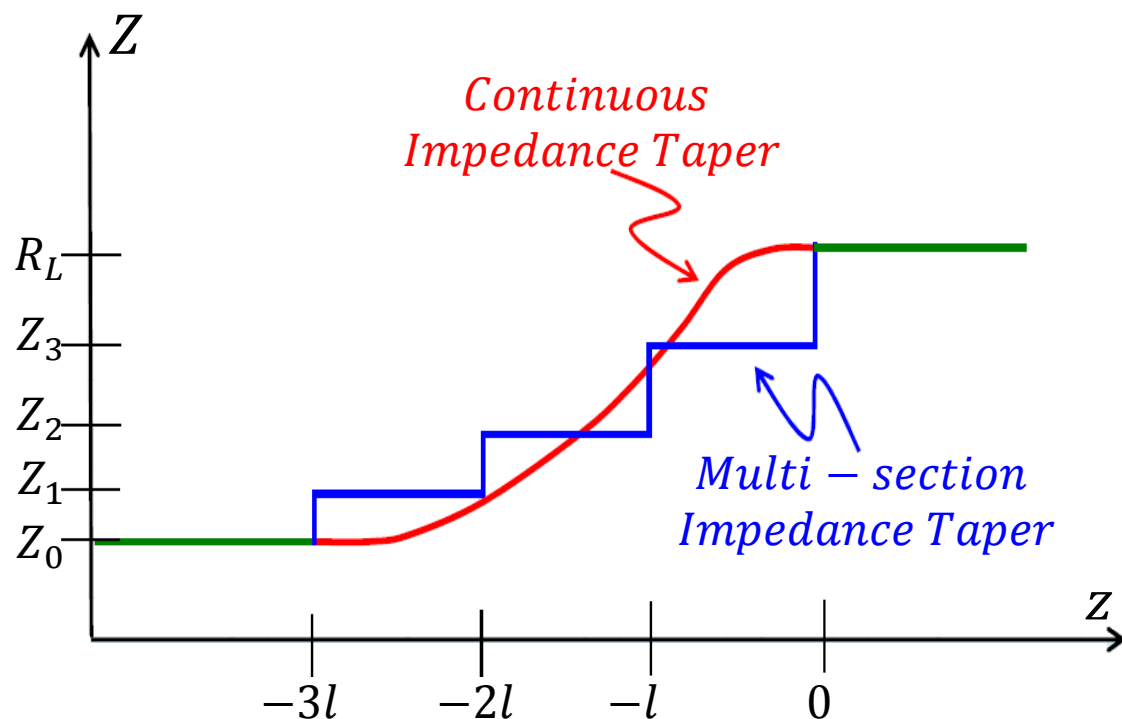


Chebyshev Multi-section Matching Transformer

Self Study

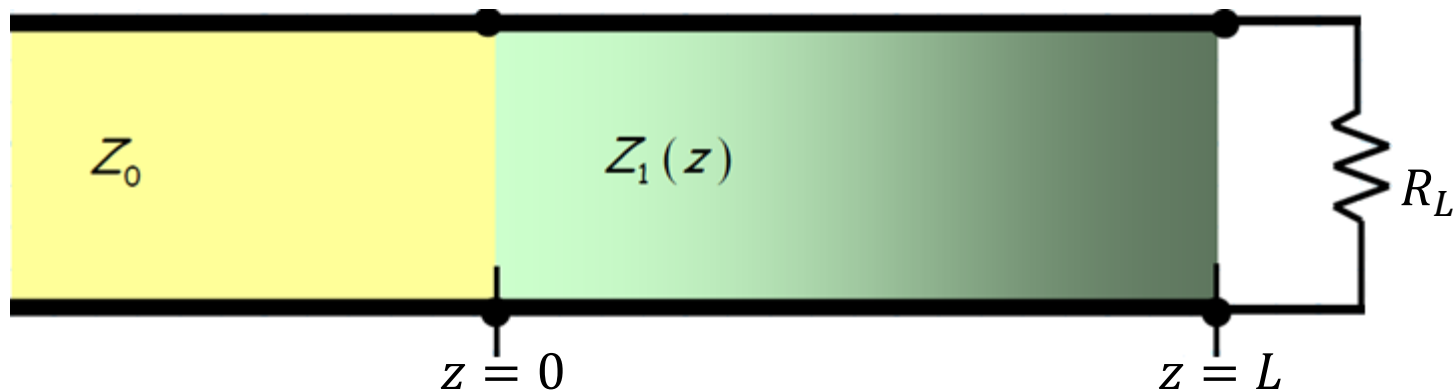
Tapered Lines

- We can also build matching networks where the characteristic impedance of a transmission line changes **continuously** with position z .
- We call these matching networks **tapered lines**.
- Note **all** our multi-section transformer designs have involved a **monotonic** change in characteristic impedance, from Z_0 to R_L (e.g., $Z_0 < Z_1 < Z_2 < \dots < R_L$).
- Now, instead of having a **stepped** change in characteristic impedance as a function of position z (i.e., a multi-section transformer), we can also design matching networks with **continuous tapers**.



Tapered Lines (contd.)

- A tapered impedance matching network is defined by **two** characteristics—its **length** L and its taper **function** $Z_1(z)$.



There are of course an **infinite** number of possible functions $Z_1(z)$. Your book discusses **three**: the **exponential** taper, the **triangular** taper, and the **Klopfenstein** taper.

Tapered Lines (contd.)

- For example, the **exponential** taper has the form:

$$Z_1(z) = Z_0 e^{az} \quad 0 < z < L$$

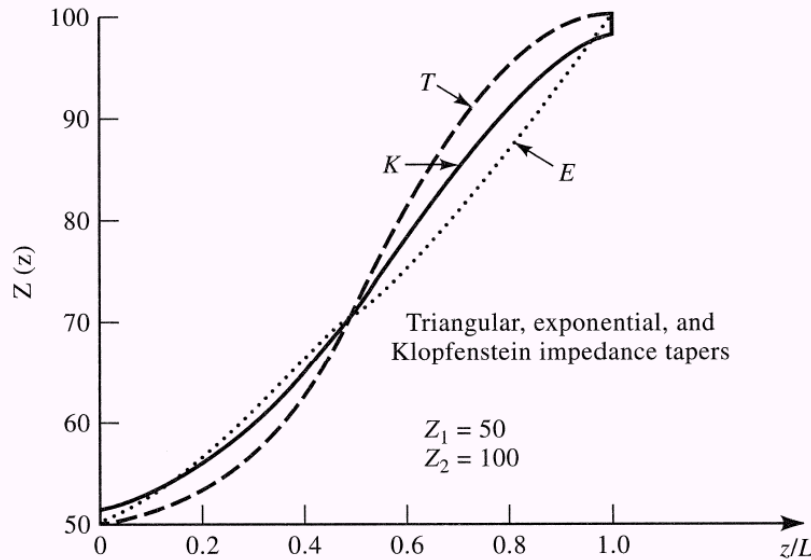
- where:

$$a = \frac{1}{L} \ln \left(\frac{Z_L}{Z_0} \right)$$

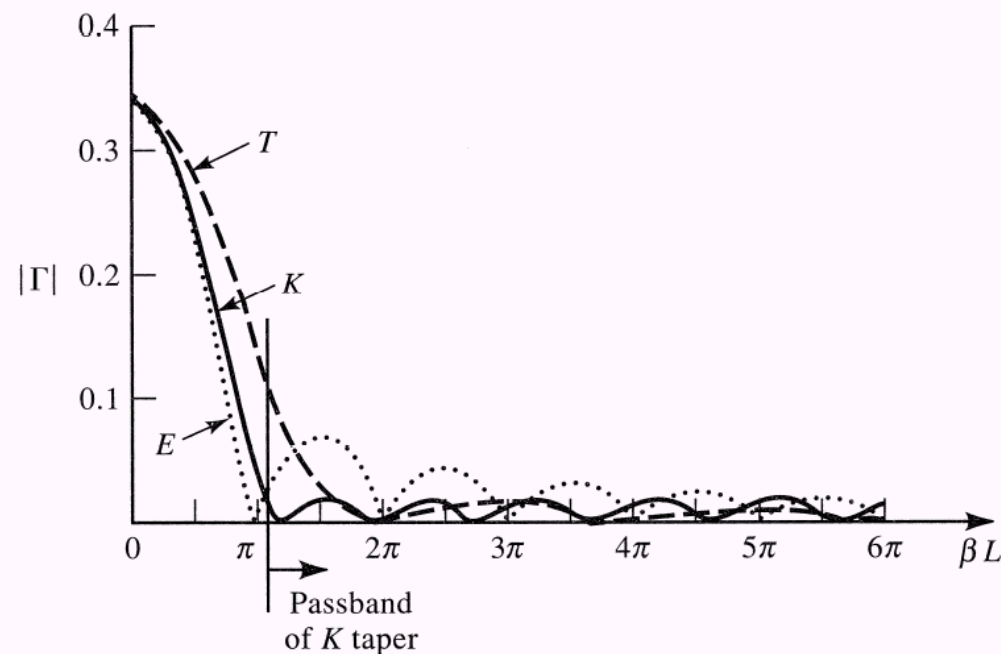
Note for the exponential taper, we get the **expected** result that $Z_1(z = 0) = Z_0$ and $Z_1(z = L) = R_L$.

Recall the **bandwidth** of a multi-section matching transformer **increases** with the **number** of sections. Similarly, the bandwidth of a tapered line will typically **increase** as the **length** L is increased.

Tapered Lines (contd.)



Impedance variations for the
triangular, exponential, and
Klopfenstein tapers.



Resulting reflection
coefficient magnitude versus
frequency for the tapers

Tapered Lines (contd.)

Q: But how can we **physically** taper the characteristic impedance of a transmission line?

A: Most tapered lines are implemented in **stripline** or **microstrip**. As a result, we can modify the characteristic impedance of the transmission line by simply tapering the **width** W of the conductor (i.e., $W(z)$).

In other words, we can **continuously** increase or decrease the **width** of the microstrip or stripline to create the **desired** impedance taper $Z_1(z)$.