

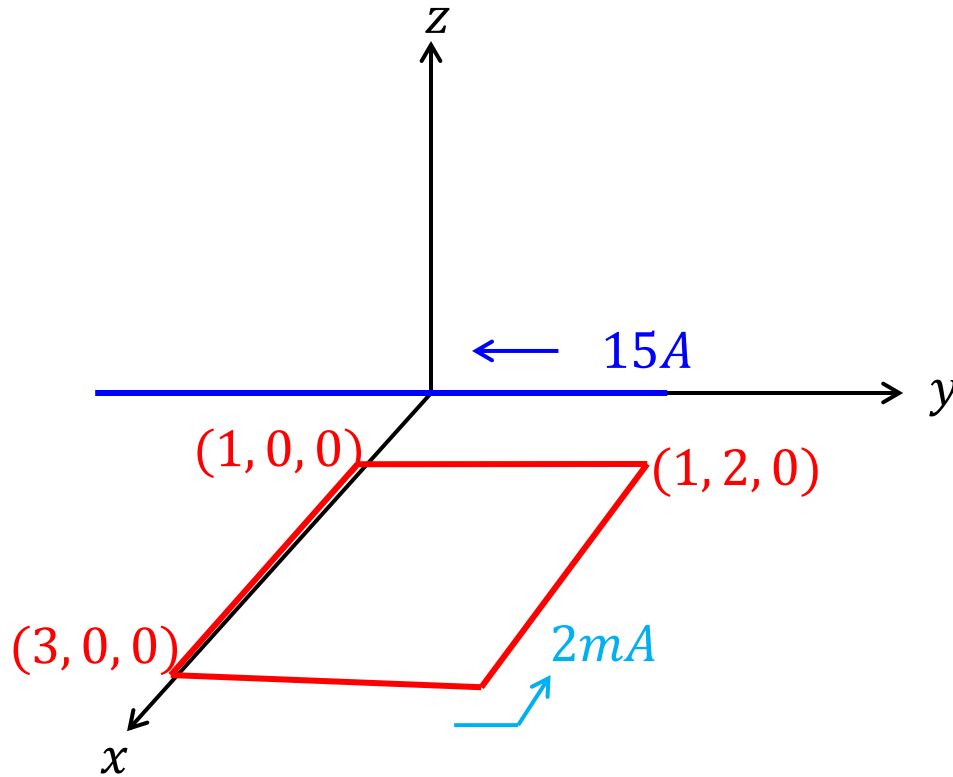
Lecture – 15

Date: 12.03.2015

- Magnetic Torque, Dipole and Moment
- Magnetization in Materials
- Magnetic Field in Materials

Example – 1

- There is a square loop of wire in the $z = 0$ plane carrying $2mA$ in the field of an infinite filament on the $y - axis$ as shown. Find the total force on the loop.



Example – 1 (contd.)

- The field produced by the straight filament in the plane of the loop is:

$$\vec{H} = \frac{I}{2\pi x} \hat{a}_z \text{ A/m}$$



$$\vec{B} = \mu_0 \vec{H} = \frac{\mu_0 I}{2\pi x} \hat{a}_z = \frac{3 \times 10^{-6}}{x} \hat{a}_z \text{ T}$$

- Therefore:

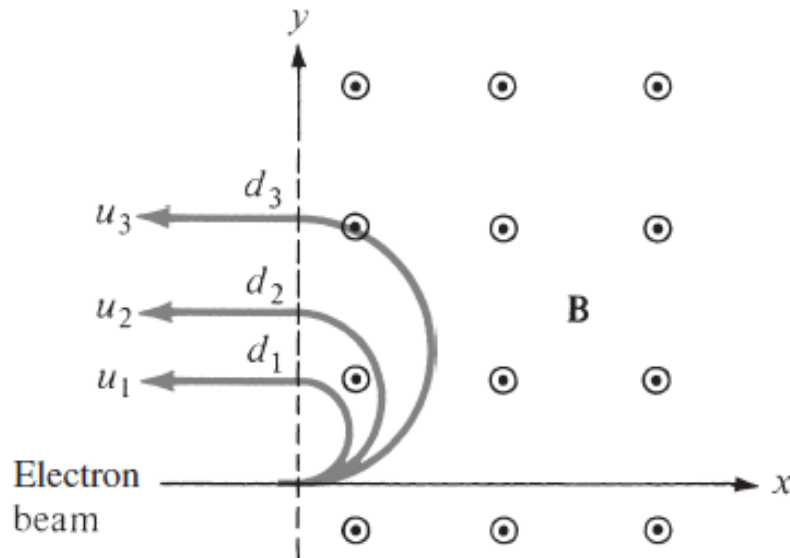
$$\vec{F}_m = I_{loop} \oint d\vec{l} \times \vec{B}$$

$$\Rightarrow \vec{F}_m = 2 \times 10^{-3} \times 3 \times 10^{-6} \left[\int_{x=1}^3 dx \hat{a}_x \times \frac{\hat{a}_z}{x} + \int_{y=0}^2 dy \hat{a}_y \times \frac{\hat{a}_z}{3} + \int_{x=3}^1 dx \hat{a}_x \times \frac{\hat{a}_z}{x} + \int_{y=2}^0 dy \hat{a}_y \times \frac{\hat{a}_z}{1} \right]$$

$$\therefore \vec{F}_m = -8 \hat{a}_x \mu\text{N}$$


Example – 2

- By injecting an electron beam normally to the plane edge of a uniform field $B_0 \hat{a}_z$, electrons can be dispersed according to their velocity as shown in the figure below.



- Show that the electrons would be ejected out of the field in path parallel to the input beam as shown.
- Derive an expression for the exit distance d above the entry point.

Example – 2 (contd.)

(a) We know: $\vec{F} = m\vec{a} = Q(\vec{u} \times \vec{B})$  $\vec{F} = m\vec{a} = -e(\vec{u} \times \vec{B})$

$$\Rightarrow -\frac{m}{e} \frac{d\vec{u}}{dt} = \begin{vmatrix} \vec{a}_x & \vec{a}_y & \vec{a}_z \\ u_x & u_y & u_z \\ 0 & 0 & B_0 \end{vmatrix} \quad \img alt="orange arrow" data-bbox="384 364 497 410"/> \quad \frac{m}{e} \frac{d\vec{u}}{dt} = -u_y B_0 \vec{a}_x + u_x B_0 \vec{a}_y$$

- From the above expression we can deduce:

$$\frac{du_x}{dt} = -u_y \frac{eB_0}{m} = -u_y g \quad \text{Where: } g = \frac{eB_0}{m}$$

$$\frac{du_y}{dt} = u_x \frac{eB_0}{m} = u_x g$$

$$\frac{du_z}{dt} = 0 \quad \img alt="orange arrow" data-bbox="231 884 344 930"/> \quad u_z = c = 0$$

Example – 2 (contd.)

- In order to determine the terms u_x and u_y , let us combine and simplify the expressions. It results into:

$$\frac{d^2 u_x}{dt^2} = -g \frac{d^2 u_y}{dt^2} = -g^2 u_x \quad \longrightarrow \quad \frac{d^2 u_x}{dt^2} + g^2 u_x = 0$$

- The solution is: $u_x = A \cos gt + B \sin gt$
- Similarly: $u_y = A \sin gt - B \cos gt$
- Let us assume: at $t = 0 \rightarrow u_x = u_0, u_y = 0$
- Then: $A = u_0$ and $B = 0$
- Therefore:

$$u_x = u_0 \cos gt \quad \longrightarrow \quad \frac{dx}{dt} = u_0 \cos gt \quad \longrightarrow \quad x = \frac{u_0}{g} \sin gt + c_1$$

$$u_y = u_0 \sin gt \quad \longrightarrow \quad \frac{dy}{dt} = u_0 \sin gt \quad \longrightarrow \quad y = -\frac{u_0}{g} \cos gt + c_2$$

Example – 2 (contd.)

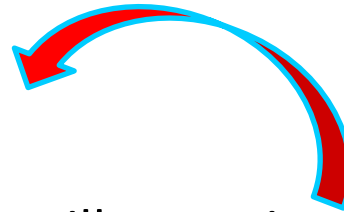
- At $t = 0$: $x = 0$ and $y = 0$

- It gives: $c_1 = 0$ and $c_2 = \frac{u_0}{g}$

- Therefore:

$$x = \frac{u_0}{g} \sin gt \quad y = \frac{u_0}{g} (1 - \cos gt)$$

- Eventually: $x^2 + \left(y - \frac{u_0}{g}\right)^2 = \left(\frac{u_0}{g}\right)^2$

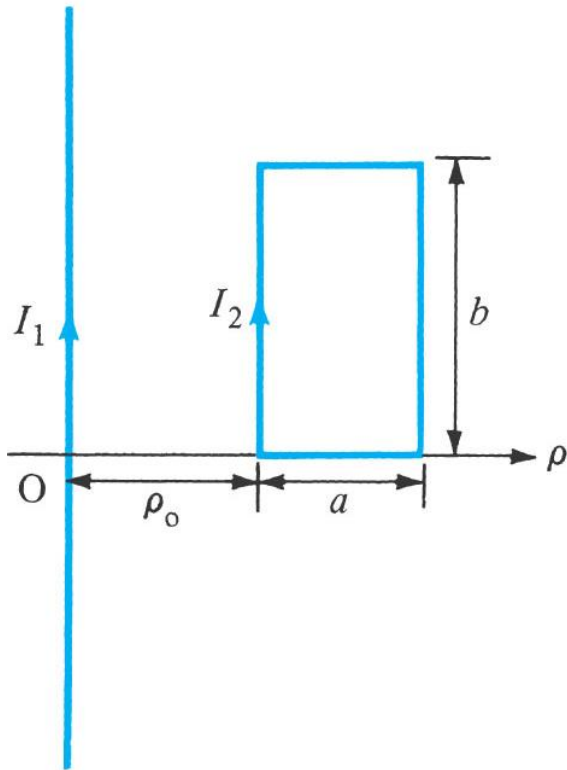


It shows that the electron will move in a circle centered at $\left(0, \frac{u_0}{g}\right)$. But since the field does not exist throughout the circular region, the electron passes through a semi-circle and leaves the field horizontally.

(b) Its twice the radius of the semi circle: $d = \frac{2u_0}{g} = \frac{2u_0 m}{B_0 e}$

Example – 3

- A rectangular loop carrying current I_2 is placed parallel to infinitely long filamentary wire carrying current I_1 as shown in figure. Show that the force experienced by the loop is given by:



$$\vec{F}_m = -\frac{\mu_0 I_1 I_2 b}{2\pi} \left[\frac{1}{\rho_0} - \frac{1}{\rho_0 + a} \right] \hat{a}_\rho \text{ N}$$

Example – 3 (contd.)

- Let the force on the loop be: $\vec{F}_m = \vec{F}_1 + \vec{F}_2 + \vec{F}_3 + \vec{F}_4$

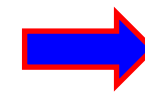
$$= I_2 \oint \vec{dl}_2 \times \vec{B}_1$$

For infinitely long wire:

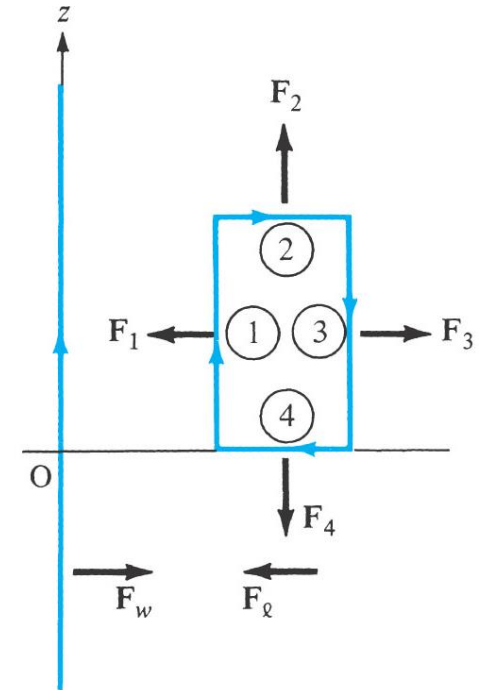
$$\vec{B}_1 = \frac{\mu_0 I_1}{2\pi\rho_0} \hat{a}_\phi$$

Therefore:

$$\vec{F}_1 = I_2 \int \vec{dl}_2 \times \vec{B}_1 = I_2 \int_{z=0}^b dz \hat{a}_z \times \frac{\mu_0 I_1}{2\pi\rho_0} \hat{a}_\phi$$



$$\vec{F}_1 = -\frac{\mu_0 I_1 I_2 b}{2\pi\rho_0} \hat{a}_\rho$$



Example – 3 (contd.)

- Similarly

$$\vec{F}_3 = I_2 \int \overline{dl}_2 \times \vec{B}_1 = I_2 \int_{z=b}^a dz \hat{a}_z \times \frac{\mu_0 I_1}{2\pi(\rho_0 + a)} \hat{a}_\phi \quad \Rightarrow \quad \vec{F}_3 = \frac{\mu_0 I_1 I_2 b}{2\pi(\rho_0 + a)} \hat{a}_\rho$$

$$\vec{F}_2 = I_2 \int_{\rho=\rho_0}^{\rho_0+a} d\rho \hat{a}_\rho \times \frac{\mu_0 I_1}{2\pi\rho} \hat{a}_\phi \quad \Rightarrow \quad \vec{F}_2 = \hat{a}_z \frac{\mu_0 I_1 I_2}{2\pi} \ln \frac{\rho_0 + a}{\rho_0}$$

$$\vec{F}_4 = I_2 \int_{\rho=\rho_0+a}^{\rho_0} d\rho \hat{a}_\rho \times \frac{\mu_0 I_1}{2\pi\rho} \hat{a}_\phi \quad \Rightarrow \quad \vec{F}_4 = -\hat{a}_z \frac{\mu_0 I_1 I_2}{2\pi} \ln \frac{\rho_0 + a}{\rho_0}$$

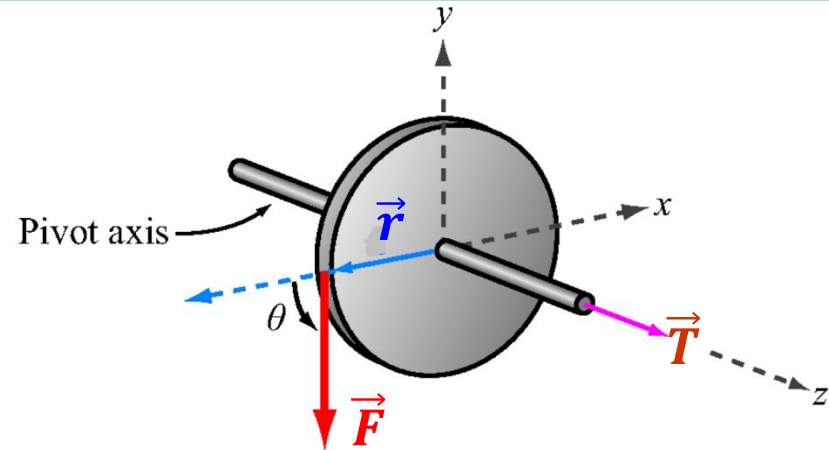
- The summation of all these expressions give the force on the loop:

$$\vec{F}_m = -\frac{\mu_0 I_1 I_2 b}{2\pi} \left[\frac{1}{\rho_0} - \frac{1}{\rho_0 + a} \right] \hat{a}_\rho \text{ N}$$

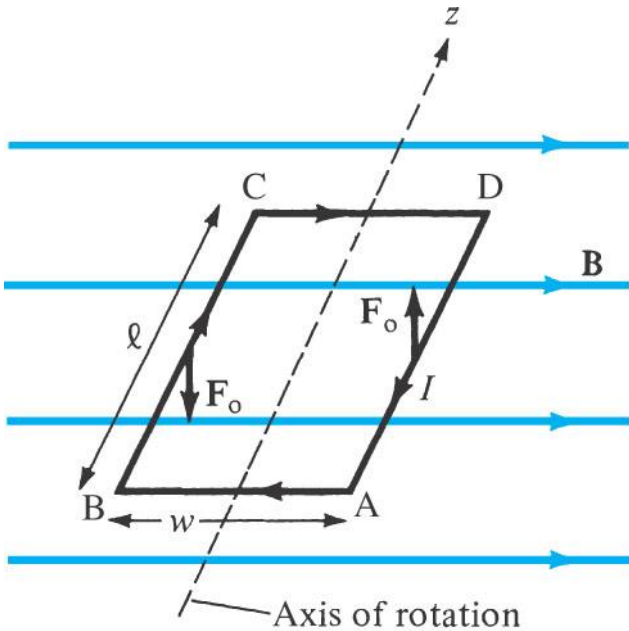
Magnetic Torque

- The torque \vec{T} is the vector product of the force \vec{F} and the moment arm \vec{r} .

$$\vec{T} = \vec{r} \times \vec{F}$$



- For the following configuration, the force on the loop is given by:



$$\vec{F} = I \int_B^C \vec{dl} \times \vec{B} + I \int_D^A \vec{dl} \times \vec{B}$$

$$\vec{F} = I \int_0^l dz \hat{a}_z \times \vec{B} + I \int_l^0 dz \hat{a}_z \times \vec{B}$$

$$\therefore \vec{F} = \vec{F}_0 + (-\vec{F})_0 = 0$$

Magnetic Torque (contd.)

- Where: $|\vec{F}_0| = IBl$  \vec{B} is considered uniform here

- Apparently no force is exerted on the loop \rightarrow however, \vec{F}_0 and $-\vec{F}_0$ acts on two different points on the loop, thereby creating a couple.
- If normal to the loop plane makes an angle α with \vec{B} then:

$$|\vec{T}| = BIlw \sin \alpha \quad \rightarrow \quad |\vec{T}| = BIS \sin \alpha$$

Let us define a quantity: $\vec{m} = IS\hat{a}_n$

Magnetic dipole moment

- Therefore: $\vec{T} = \vec{m} \times \vec{B}$
- Although this expression is obtained for rectangular loop but is applicable for planar loop of any arbitrary shape.

Example – 4

- A rectangular coil of area 10 cm^2 carrying current 50 A lies on plane $2x + 6y - 3z = 7$ such that the magnetic moment of the coil is directed away from the origin. Calculate its magnetic moment.

$$f(x, y, z) = 2x + 6y - 3z = 0$$



$$\hat{a}_n = \pm \frac{\nabla f}{|\nabla f|} = \frac{2\hat{a}_x + 6\hat{a}_y - 3\hat{a}_z}{|\sqrt{49}|}$$

$$\vec{m} = IS\hat{a}_n$$



$$\vec{m} = 10 \times 10^{-4} \times 50 \times \frac{(2\hat{a}_x + 6\hat{a}_y - 3\hat{a}_z)}{|\sqrt{49}|}$$

$$\vec{m} = 7.143 \times 10^{-3} \times (2\hat{a}_x + 6\hat{a}_y - 3\hat{a}_z)$$



$$\vec{m} = (1.429\hat{a}_x + 4.286\hat{a}_y - 2.143\hat{a}_z) \times 10^{-2} \text{ A.m}^2$$

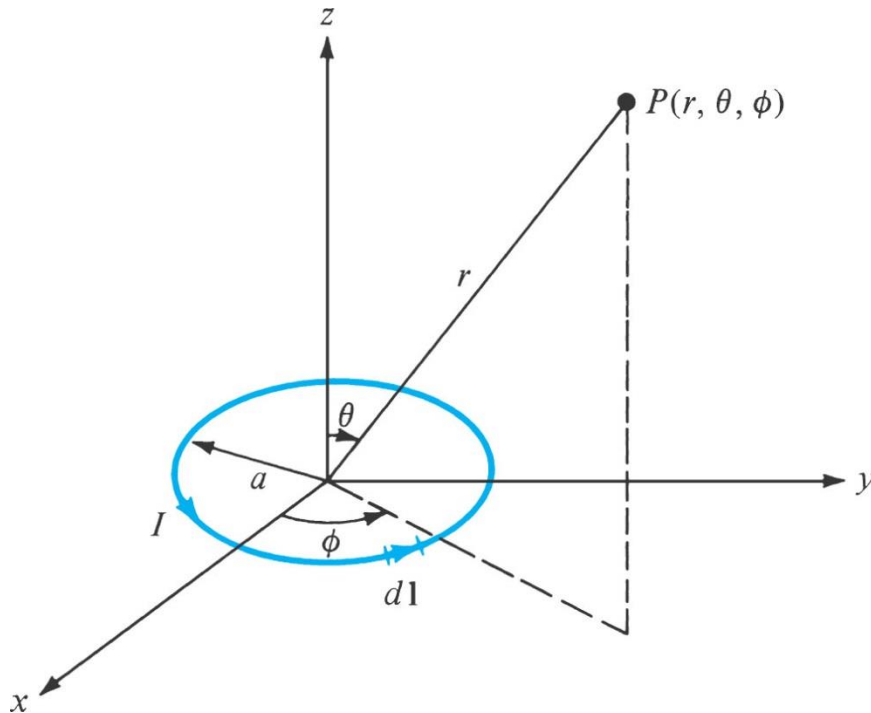
Example – 5

- The coil of last example is surrounded by a uniform field $0.6\hat{a}_x + 0.4\hat{a}_y + 0.5\hat{a}_z \text{ Wb/m}^2$.
- (a) Find the torque on the coil.
- (b) Show that the torque on the coil is maximum if placed on plane $2x - 8y + 4z = \sqrt{84}$. Calculate the magnitude of the maximum torque.

$$\vec{T} = \vec{m} \times \vec{B} \quad \longrightarrow \quad \vec{T} = \begin{vmatrix} \vec{a}_x & \vec{a}_y & \vec{a}_z \\ m_x & m_y & m_z \\ B_x & B_y & B_z \end{vmatrix}$$

Magnetic Dipole

- A bar magnet or small filamentary current loop is usually referred to as a magnetic dipole.
- The reason will be soon apparent.
- Let us consider the magnetic field \vec{B} at an observation point $P(r, \theta, \phi)$ due to a circular loop carrying current I .



- The magnetic vector potential at P is:

$$\vec{A} = \frac{\mu_0 I}{4\pi} \oint \frac{d\vec{l}}{r}$$

Magnetic Dipole (contd.)

$$\vec{A} = \frac{\mu_0 \vec{m} \times \hat{a}_r}{4\pi r^2}$$

$$\vec{B} = \nabla \times \vec{A} = \frac{\mu_0 m}{4\pi r^3} (2 \cos \theta \hat{a}_r + \sin \theta \hat{a}_\theta)$$

These are similar to the expressions for V and \vec{E}
due to an electric dipole

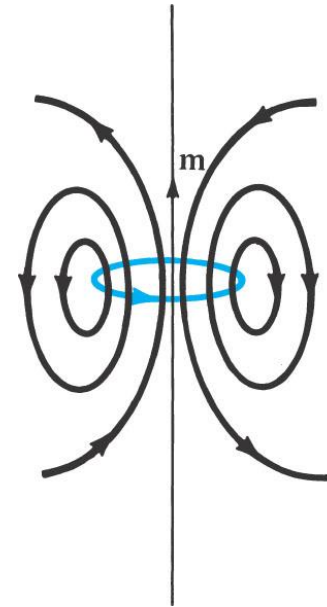
$$V = \frac{\vec{p} \cdot \hat{a}_r}{4\pi \epsilon_0 r^2}$$

$$\vec{E} = -\nabla V = \frac{p}{4\pi \epsilon_0 r^3} (2 \cos \theta \hat{a}_r + \sin \theta \hat{a}_\theta)$$

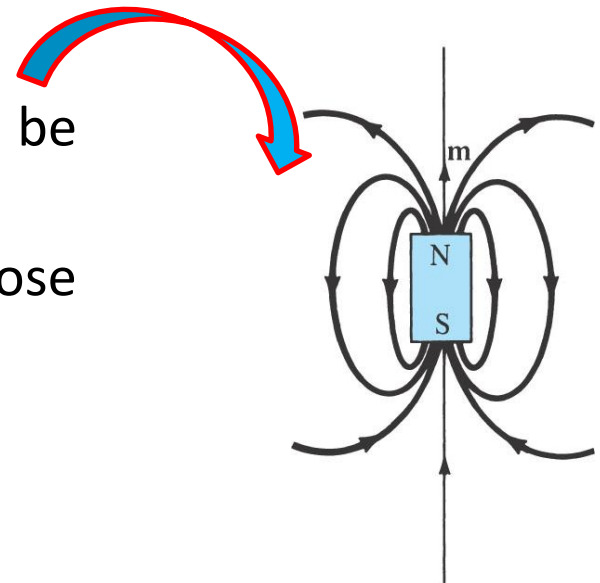
It is therefore reasonable to regard a small current
loop as a magnetic dipole

Magnetic Dipole (contd.)

- \vec{B} lines around the magnetic dipole can be illustrated as:



- A short permanent magnet can also be considered as a magnetic dipole.
- The \vec{B} lines due to bar are similar to those due to a small current loop.



Magnetic Materials

- Recall in dielectrics, electric dipoles were created when an $\vec{E} - field$ was applied.
- Therefore, we defined permittivity ϵ , electric flux density \vec{D} , and a new set of electrostatic equations.
- Recall that **atoms and molecules**, having both positive (i.e., protons) and negative (i.e., electron) charged particles can form **electric dipoles**.
- It will be apparent that that atoms and molecules can also form **magnetic dipoles!**

Q: How??


A: Recall a magnetic dipole is formed when current flows in a **small loop**. Current, of course, is **moving charge**, therefore charge moving around a small loop forms a magnetic dipole.

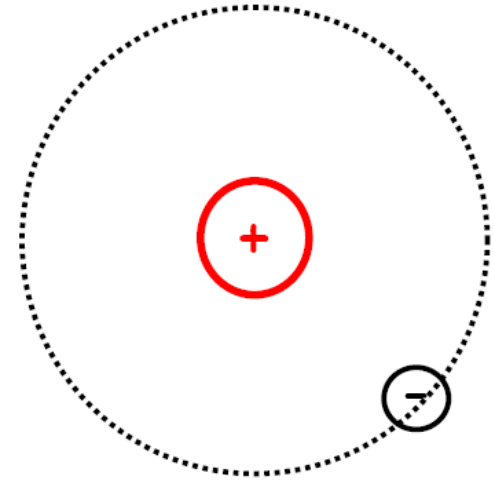
Molecules and atoms **often** exhibit electrons moving around in small loops!

Magnetic Materials (contd.)

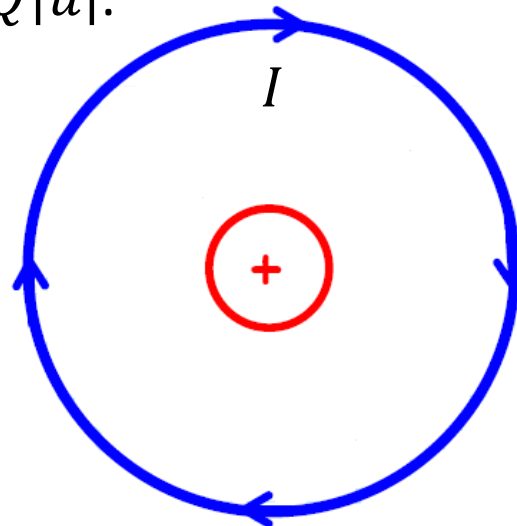
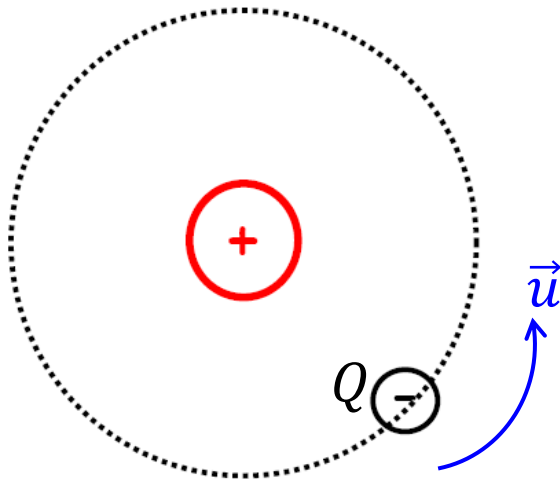
- Again, let us use our **ridiculously** simple model of an atom:

 → electron
(negative charge)

 → nucleus
(positive charge)



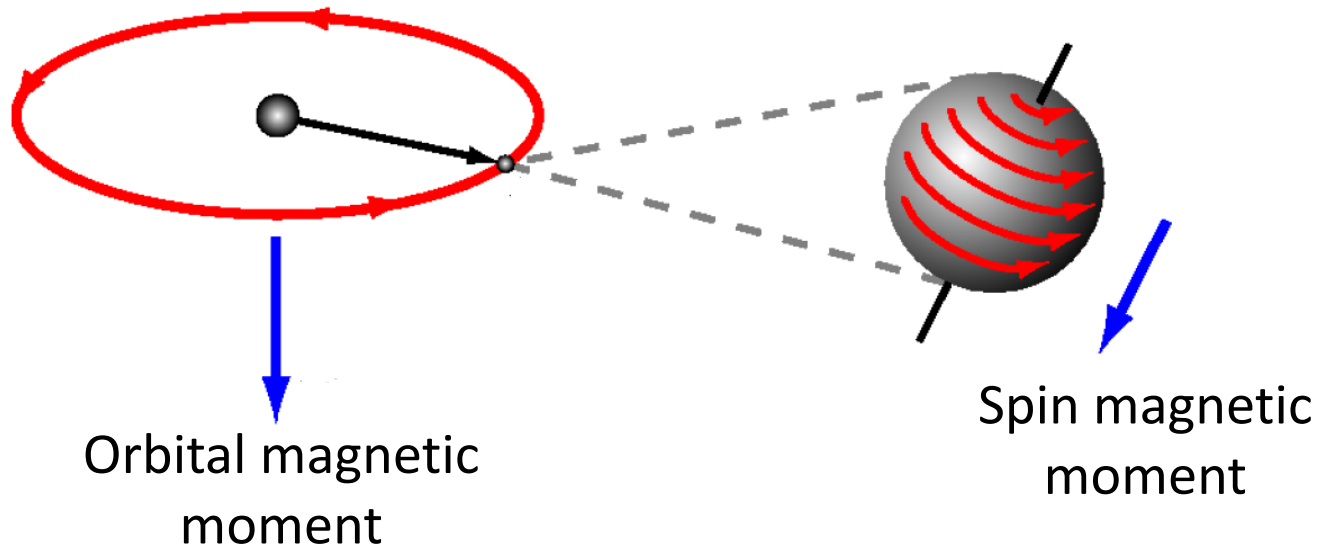
- An electron with charge Q orbiting around a nucleus at velocity \vec{u} forms a **small current loop**, where $I = Q|\vec{u}|$.



 This forms a
magnetic
dipole

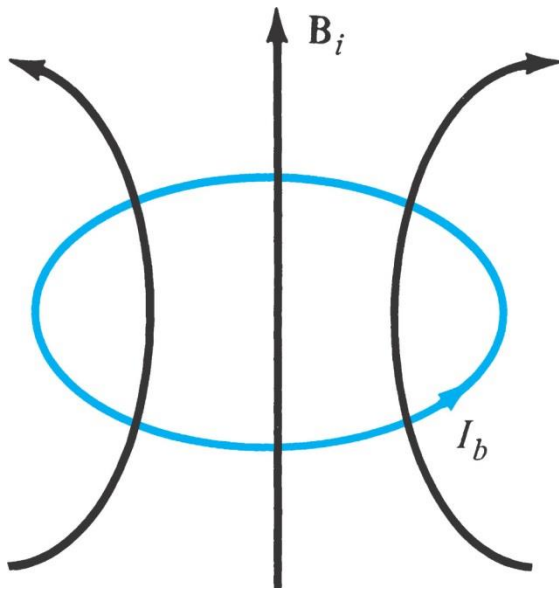
Magnetic Materials (contd.)

- This is a **very simple** atomic explanation of how magnetic dipoles are formed in material.
- In reality, the physical mechanisms that lead to magnetic dipoles can be **far** more complex.
- For example, **electron spin** can also create a magnetic dipole moment.



Magnetic Materials (contd.)

- Both these electronic motions produce internal magnetic fields \vec{B}_i that are similar to the magnetic field produced by a current loop as shown.



This equivalent current loop has a magnetic moment of $\vec{m} = I_b S \hat{a}_n$, where S is the area of the loop and I_b is the bound current (bound to the atom).

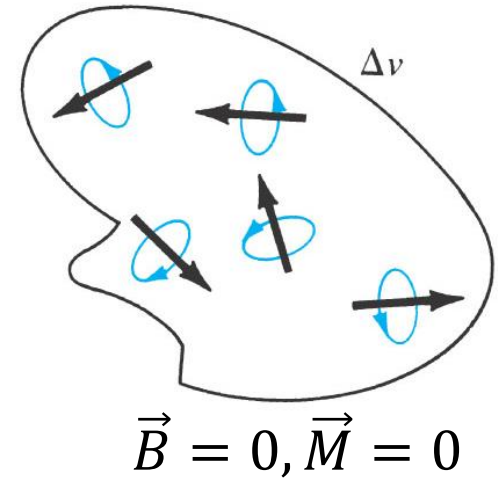
Magnetic Materials (contd.)

- Typically, the atoms/molecules of materials exhibit either **no** magnetic dipole moment (i.e., $\vec{m} = 0$), or the dipole moments of each atom/molecule are **randomly oriented**, such that the **net** dipole moment is **zero**.
- Therefore, for N randomly oriented magnetic dipoles \vec{m}_n , we find:

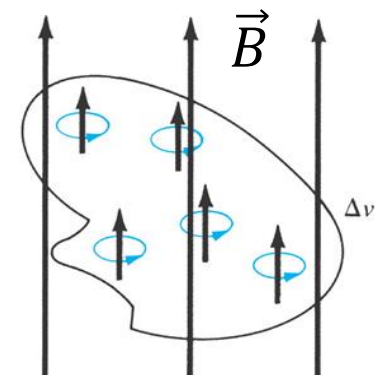
$$\frac{1}{N} \sum_n \vec{m}_n = 0$$

- Similarly, the **total** magnetic flux density created by these magnetic dipoles is **also zero**:

$$\sum_n \vec{B}_n = 0$$



- However, sometimes the magnetic dipole moment of each atom/molecule is **not** randomly oriented, but in fact are **aligned**!



Magnetic Materials (contd.)

Q: Why would these magnetic dipoles be aligned?

A: Two possible reasons:

- 1)** the material is a **permanent magnet**.
- 2)** the material is immersed in some **magnetizing field \vec{B}** .

The Magnetization Vector

- Recall that we defined the **Polarization vector** of a dielectric material as the **electric dipole density**, i.e.:

$$\vec{P} \doteq \frac{\sum \vec{p}_n}{\Delta v} \left[\frac{\text{dipole_moment}}{\text{unit_volume}} = \frac{C}{m^2} \right]$$

- Similarly, we can define a **Magnetization vector** of a material to be the density of **magnetic** dipole moments:

$$\vec{M} \doteq \frac{\sum \vec{m}_n}{\Delta v \rightarrow 0} \left[\frac{\text{magnetic_dipole_moment}}{\text{unit_volume}} = \frac{A}{m} \right]$$

A medium for which \vec{M} is not zero everywhere is said to be magnetized

The Magnetization Vector (contd.)

- Note if the dipole moments of atoms/molecules within a material are **completely random**, the Magnetization vector will be **zero** (i.e., $\vec{M} = 0$).
- However, if the dipoles are **aligned**, the Magnetization vector will be **non-zero** (i.e., $\vec{M} \neq 0$).
- Furthermore, for a differential volume dv' , the magnetic moment is $\vec{dm} = \vec{M} dv'$.
- Therefore the vector magnetic potential due to \vec{dm} can be expressed as:

$$\vec{dA} = \frac{\mu_0 \vec{M} \times \hat{a}_R}{4\pi R^2} dv' \quad \longrightarrow \quad \vec{dA} = \frac{\mu_0 \vec{M} \times \vec{R}}{4\pi R^3} dv'$$

$$\therefore \vec{A} = \iiint_v \frac{\mu_0 \vec{M} \times \vec{R}}{4\pi R^3} dv'$$

The Magnetization Vector (contd.)

$$\therefore \vec{A} = \iiint_v \frac{\mu_0 \vec{M} \times \vec{R}}{4\pi R^3} dv'$$



Q: This is freaking me out!! I thought that **currents** \vec{J} were responsible for creating magnetic vector potential. In fact, I could have sworn that:

$$\vec{A} = \iiint_v \frac{\mu_0 \vec{J}}{4\pi R} dv'$$

A: Relax, **both** expressions are correct!

The Magnetization Currents

- Recall that we could attribute the electric field created by Polarization Vector \vec{P} to **polarization** (i.e., bound) **charges** ρ_{vp} and ρ_{sp} .

$$\rho_{vp} = -\nabla \cdot \vec{P}$$

$$\rho_{sp} = \vec{P} \cdot \hat{a}_n$$

- Similarly, we can **attribute** the magnetic vector potential (and therefore the magnetic flux density) created by Magnetization Vector \vec{M} to **Magnetization Currents** \vec{J}_b and \vec{K}_b , the bound volume current density (i.e., magnetization current density) and bound surface current density respectively.

- We have:

$$\vec{A} = \iiint_v \frac{\mu_0 \vec{M} \times \vec{R}}{4\pi R^3} dv'$$

- Earlier we came across the expression:

$$\frac{\vec{R}}{R^3} = \nabla' \left(\frac{1}{R} \right)$$

- Therefore:

$$\vec{A} = \frac{\mu_0}{4\pi} \iiint_v \vec{M} \times \nabla' \left(\frac{1}{R} \right) dv'$$

The Magnetization Currents (contd.)

- We can use the identity:
$$\vec{M} \times \nabla' \left(\frac{1}{R} \right) = \frac{1}{R} \nabla' \times \vec{M} - \nabla' \times \frac{\vec{M}}{R}$$

- Therefore we can express:
$$\vec{A} = \frac{\mu_0}{4\pi} \iiint_v \frac{\nabla' \times \vec{M}}{R} dv' + \frac{\mu_0}{4\pi} \oiint_s \frac{\vec{M} \times \hat{a}_n}{R} ds'$$

$$\vec{A} = \frac{\mu_0}{4\pi} \iiint_v \frac{\vec{J}_b}{R} dv' + \frac{\mu_0}{4\pi} \oiint_s \frac{\vec{K}_b ds'}{R}$$

where:

$$\vec{J}_b = \nabla \times \vec{M}$$

$$\vec{K}_b = \vec{M} \times \hat{a}_n$$

Therefore, we find that the magnetization of some material, as described by magnetization vector \vec{M} , creates **effective** currents \vec{J}_b and \vec{K}_b . We call these effective currents **magnetization currents**.

\vec{J}_b and \vec{K}_b can be derived from \vec{M} and hence are not commonly used

The Magnetic Field

- Now that we have defined **magnetization current**, we find that Ampere's Law for fields **within some material** becomes:

$$\nabla \times \vec{B} = \mu_0 (\vec{J} + \vec{J}_b)$$

$$\nabla \times \vec{B} = \mu_0 (\vec{J} + \nabla \times \vec{M})$$

- This of course is **analogous** to the expression we derived for **Gauss's Law** in a dielectric media:

$$\nabla \cdot \vec{E} = \frac{\rho_v + \rho_{vp}}{\epsilon_0} = \frac{\rho_v - \nabla \cdot \vec{P}}{\epsilon_0}$$

Recall that we **removed** the polarization charge from this expression by defining a **new** vector field \vec{D} , leaving us with the more **general** expression of Gauss's Law:

$$\nabla \cdot \vec{D} = \rho_v$$

The Magnetic Field (contd.)

Q: Can we similarly define a **new** vector field to “take care” of **magnetization** current ??



A: Yes! We call this vector field the **magnetic field** \vec{H} .

- Let's begin by **rewriting** Ampere's Law as:

$$\nabla \times \vec{B} - \mu_0 \vec{J}_b = \mu_0 \vec{J}$$

- Yuck! Now we see clearly the problem. In **free space**, if we know current distribution \vec{J} , we can find the resulting magnetic flux density \vec{B} using the **Biot-Savart** Law:

$$\vec{B} = \frac{\mu_0}{4\pi} \iiint_v \frac{\vec{J} \times \vec{R}}{R^3} dv'$$

But this is the solution for current in **free space**! It is **no longer valid** if some **material** is present!

The Magnetic Field (contd.)

Q: Why?

A: Because, the magnetic flux density produced by current \vec{J} may **magnetize** the material (i.e., produce magnetic dipoles), thus producing **magnetization currents** \vec{J}_b .

These magnetization currents \vec{J}_b will **also** produce a magnetic flux density—a **modification** of vector field \vec{B} that is **not** accounted for in the Biot-Savart expression shown above!

- To determine the correct solution, we first recall that:

$$\vec{J}_b = \nabla \times \vec{M}$$

- Therefore Ampere's Law is:

$$\nabla \times \vec{B} - \mu_0 \nabla \times \vec{M} = \mu_0 \vec{J}$$

- Now let's define a **new** vector field \vec{H} , called the **magnetic field**:

$$\vec{H} = \frac{\vec{B}}{\mu_0} - \vec{M}$$

$$\nabla \times \left[\frac{\vec{B}}{\mu_0} - \vec{M} \right] = \vec{J}$$

- Therefore:

$$\nabla \times \vec{H} = \vec{J}$$

The Magnetic Field (contd.)

- For most materials, it has been found that the magnetization vector \vec{M} is directly **proportional** to the magnetic field \vec{H} :
$$\vec{M} = \chi_m \vec{H}$$
where the proportionality coefficient χ_m is the **magnetic susceptibility** of the material.
- Note that for a given magnetic field \vec{H} , as χ_m **increases**, the magnetization vector \vec{M} **increases**.
- Magnetic susceptibility χ_m therefore indicates how **susceptible** the material is to **magnetization**.
- In other words, χ_m is a measure of how easily (or difficult) it is to create and align **magnetic dipoles** (from atoms/molecules) within the **material**.

Again, note the **analogy** to electrostatics. We defined earlier **electric** susceptibility χ_e , which indicates how susceptible a material is to **polarization** (i.e., the creation of **electric** dipoles).

The Magnetic Field (contd.)

- Therefore: $\vec{H} = \frac{\vec{B}}{\mu_0} - \vec{M}$ \rightarrow $\vec{H} = \frac{\vec{B}}{\mu_0} - \chi_m \vec{H}$ \rightarrow $\mu_0(1 + \chi_m)\vec{H} = \vec{B}$

Hey! We know the magnetic field \vec{H} and magnetic flux density are related by a **simple constant!**

$$\vec{B} = \mu \vec{H}$$


$$\therefore \mu = \mu_0(1 + \chi_m)$$

$$\mu \doteq \text{material_permeability} \left[\frac{\text{Henrys}}{\text{meter}} \right]$$

- The expression can be **further** simplified by defining a **relative** permeability:

$$\mu_r = 1 + \chi_m$$

The Magnetic Field (contd.)

- Therefore: $\vec{B} = \mu \vec{H} = \mu_0 \mu_r \vec{H}$  Only valid for linear isotropic materials
- In other words, if the **relative** permeability of some material was, say, $\mu_r = 2$, then the **permeability** of the material is **twice** that of the permeability of **free space** (i.e., $\mu = 2\mu_0$). This perhaps is more readily evident when we write:

$$\mu_r = \frac{\mu}{\mu_0}$$

Note that μ and/or μ_r are **proportional** to magnetic susceptibility χ_m . As a result, permeability is likewise an indication of how **susceptible** a material is to **magnetization**.

- If $\mu_r = 1$, this susceptibility is that of **free space** (i.e., **none!**).
- Alternatively, a **large** μ_r indicates a material that is **easily magnetized**.
- For example, the relative permeability of **iron** is $\mu_r = 4000$!

The Magnetic Field (contd.)

- **Now**, we are **finally** able to determine the **magnetic flux density** in some **material**, produced by current density \vec{J} !
- Since $\vec{B} = \mu\vec{H}$ and:

$$\vec{H} = \frac{1}{4\pi} \iiint_v \frac{\vec{J} \times \vec{R}}{R^3} dv'$$

- we find the desired solution:

$$\vec{B} = \frac{\mu}{4\pi} \iiint_v \frac{\vec{J} \times \vec{R}}{R^3} dv'$$

Comparing this result with the Biot-Savart Law for **free space**, we see that the only difference is that μ_0 has been replaced with μ .

This last result is therefore a **more general** form of the Biot-Savart Law, giving the correct result for fields within some **material** with permeability μ . Of course, the “material” **could** be free space. However, the expression above will **still** provide the **correct** answer; because for free space $\mu = \mu_0$, thus returning the equation to its **original** (i.e., free space) form!

The Magnetic Field (contd.)

Summarizing, we can attribute the existence of a **magnetic field** \vec{H} to **conduction** current \vec{J} , while we attribute the existence of **magnetic flux density** to the **total** current density, including the magnetization current.