

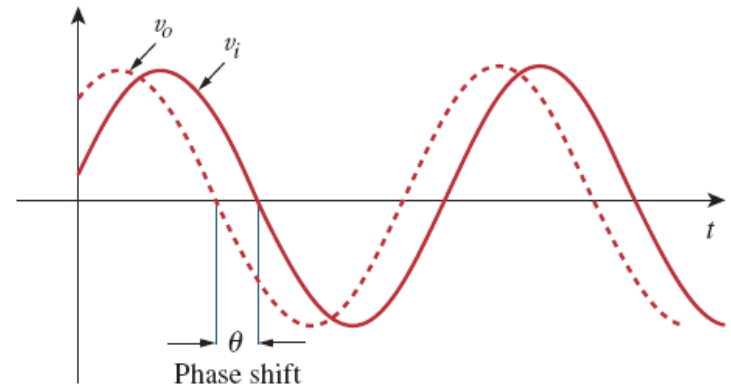
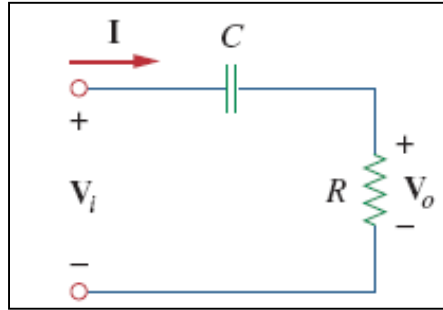
# ECE 215

## Lecture – 8

Date: 28.08.2017

- Phase Shifter, AC bridge
- AC Circuits: Steady State Analysis

# Phase Shifter



the circuit current  $I$  leads the applied voltage by some phase angle  $\theta$ , where  $0 < \theta < 90^\circ$  depending on the values of  $R$  and  $C$ .

$$Z = R + jX_C \longrightarrow \theta = \tan^{-1} \frac{X_C}{R}$$

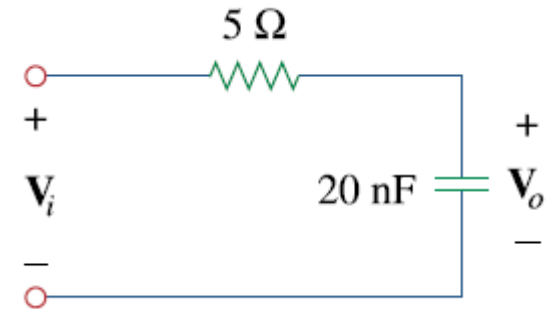
the amount of phase shift depends on the values of  $R$ ,  $C$ , and the operating frequency.

- These simple single stage RC circuits are generally not used in practice.
- These RC circuits also work as voltage dividers. Therefore, as the phase shift approaches  $90^\circ$  the output voltage approaches zero. Therefore, the simple RC circuits are used only when small amounts of phase shift are required.
- For large phase shifts, the RC networks are cascaded. This provides a total phase shift equal to the sum of the individual phase shifts.

## Example – 1

For this RC circuit:

- Calculate the phase shift at 2 MHz.
- Find the frequency where the phase shift is  $45^\circ$ .



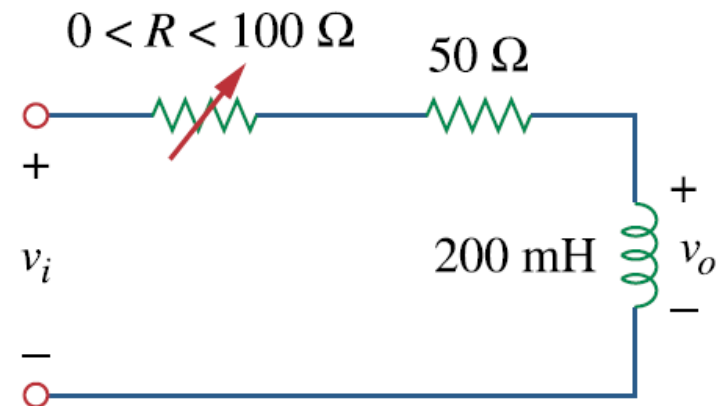
## Example – 2

A coil with impedance  $8 + j6 \Omega$  is connected in series with a capacitive reactance  $X$ . The series combination is connected in parallel with a resistor  $R$ . Given that the equivalent impedance of the resulting circuit is  $5 \angle 0^\circ \Omega$ , find the value of  $R$  and  $X$ .

## Example – 3

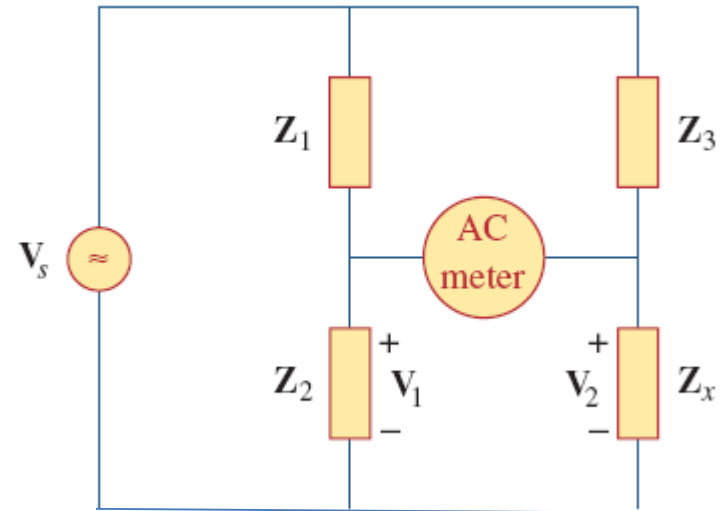
Consider this phase-shifting circuit for 60Hz and determine

- $V_o$  when  $R$  is maximum
- $V_o$  when  $R$  is minimum
- the value of  $R$  that will produce a phase shift of  $45^\circ$ .



## AC Bridges

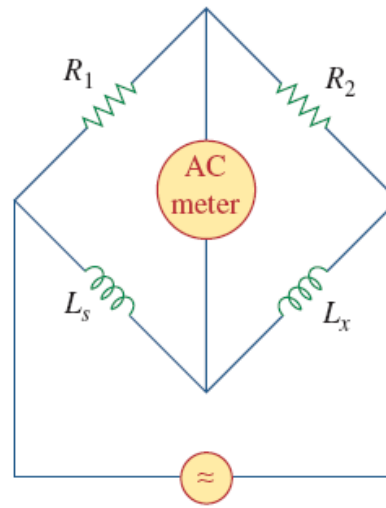
- An ac bridge circuit is used for measuring the inductance  $L$  of an inductor or the capacitance  $C$  of a capacitor.
- Similar to the Wheatstone bridge used for measuring an unknown resistance and follows the same principle.
- To measure  $L$  and  $C$ , however, an ac source is needed as well as an ac meter instead of the galvanometer.
- The ac meter may be a sensitive ac ammeter or voltmeter.



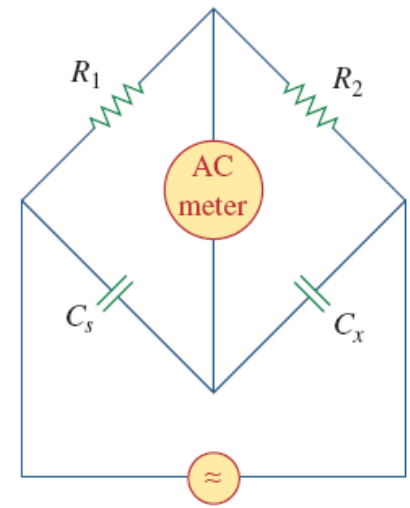
bridge is *balanced* when no current flows through the meter i.e.,  $V_1 = V_2$ .

$$V_1 = \frac{Z_2}{Z_1 + Z_2} V_s = V_2 = \frac{Z_x}{Z_3 + Z_x} V_s \quad \longrightarrow \quad Z_x = \frac{Z_3}{Z_1} Z_2$$

## AC Bridges (contd.)



$$L_x = \frac{R_2}{R_1} L_s$$

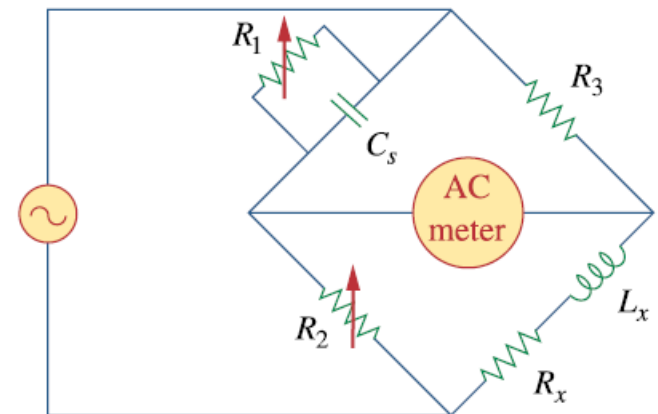


$$C_x = \frac{R_1}{R_2} C_s$$

### Example – 4

This ac bridge is known as a *Maxwell bridge* and is used for accurate measurement of inductance and resistance of a coil in terms of a standard capacitance  $C_s$ . Show that when the bridge is balanced:

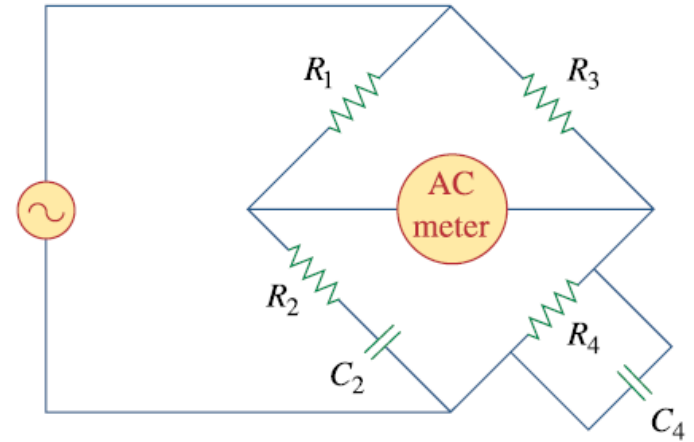
$$L_x = R_2 R_3 C_s \quad R_x = \frac{R_2}{R_1} R_3$$



## Example – 5

This ac bridge is called a *Wien bridge*. It is used for measuring the frequency of a source. Show that when the bridge is balanced:

$$f = \frac{1}{2\pi\sqrt{R_2R_4C_2C_4}}$$



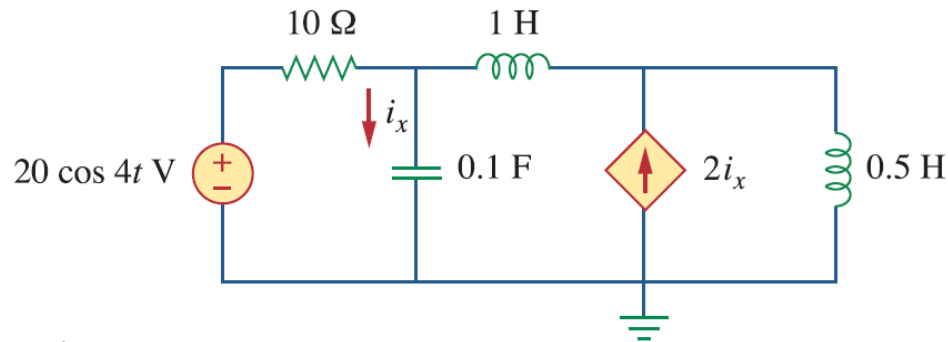
## AC Circuit – Steady State Analysis

### Analysis Steps

1. Transfer the circuit to the phasor domain
2. Solve the circuit (using Mesh, Nodal techniques etc.)
3. Convert the results into time domain

# Nodal Analysis

Find  $i_x$  in this circuit.



Convert the quantities to frequency domain.

$$20 \cos 4t \Rightarrow 20 \angle 0^\circ, \quad \omega = 4 \text{ rad/s}$$

$$1 \text{ H} \Rightarrow j\omega L = j4$$

$$0.5 \text{ H} \Rightarrow j\omega L = j2$$

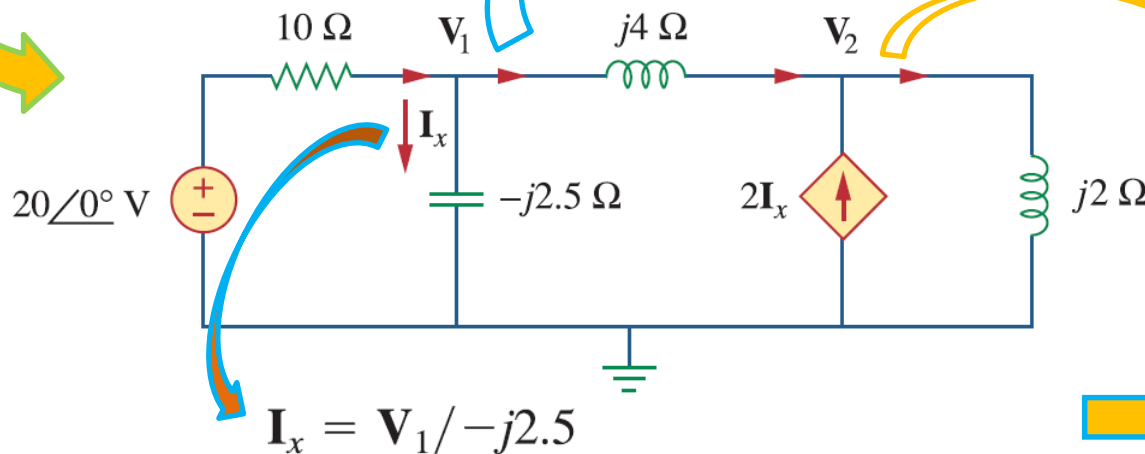
$$0.1 \text{ F} \Rightarrow \frac{1}{j\omega C} = -j2.5$$

KCL here

$$\frac{20 - V_1}{10} = \frac{V_1}{-j2.5} + \frac{V_1 - V_2}{j4}$$

$$(1 + j1.5)V_1 + j2.5V_2 = 20$$

Freq Domain



KCL here

$$2I_x + \frac{V_1 - V_2}{j4} = \frac{V_2}{j2}$$

$$\frac{2V_1}{-j2.5} + \frac{V_1 - V_2}{j4} = \frac{V_2}{j2}$$

$$11V_1 + 15V_2 = 0$$

## Nodal Analysis (contd.)

- The two nodal equations can be expressed in matrix form:

$$\begin{bmatrix} 1 + j1.5 & j2.5 \\ 11 & 15 \end{bmatrix} \begin{bmatrix} \mathbf{V}_1 \\ \mathbf{V}_2 \end{bmatrix} = \begin{bmatrix} 20 \\ 0 \end{bmatrix}$$

$$\Delta = \begin{vmatrix} 1 + j1.5 & j2.5 \\ 11 & 15 \end{vmatrix} = 15 - j5$$

$$\Delta_1 = \begin{vmatrix} 20 & j2.5 \\ 0 & 15 \end{vmatrix} = 300$$

$$\mathbf{V}_1 = \frac{\Delta_1}{\Delta} = \frac{300}{15 - j5} = 18.97 \angle 18.43^\circ \text{ V}$$

$$\Delta_2 = \begin{vmatrix} 1 + j1.5 & 20 \\ 11 & 0 \end{vmatrix} = -220$$

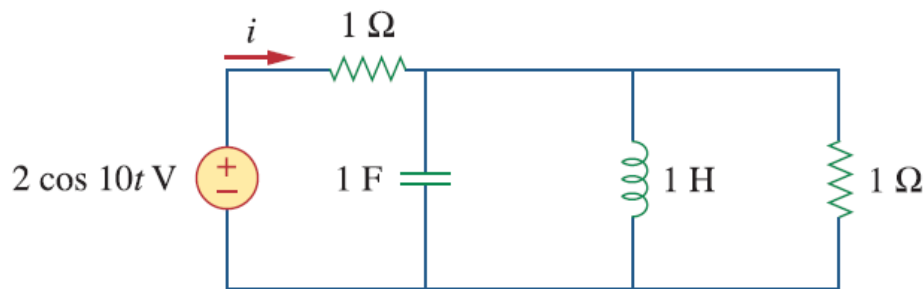
$$\mathbf{V}_2 = \frac{\Delta_2}{\Delta} = \frac{-220}{15 - j5} = 13.91 \angle 198.3^\circ \text{ V}$$

$$\mathbf{I}_x = \frac{\mathbf{V}_1}{-j2.5} = \frac{18.97 \angle 18.43^\circ}{2.5 \angle -90^\circ} = 7.59 \angle 108.4^\circ \text{ A}$$

$$i_x = 7.59 \cos(4t + 108.4^\circ) \text{ A}$$

**Practice:** Find  $i$  in this circuit.

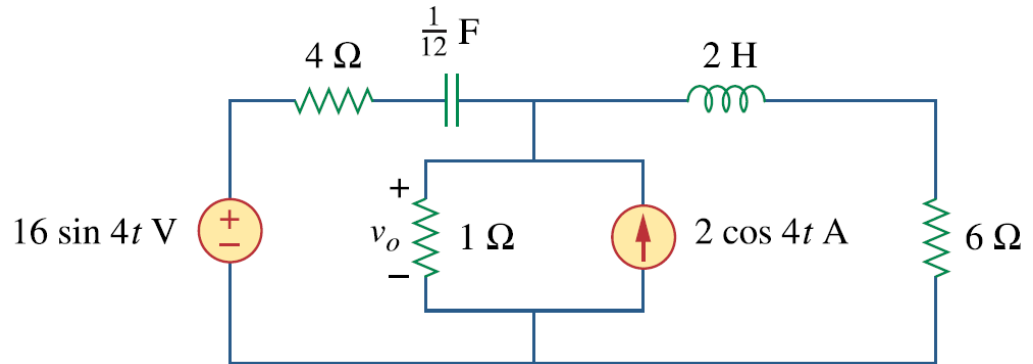
$$i(t) = \underline{1.9704 \cos(10t + 5.653^\circ) \text{ A}}$$





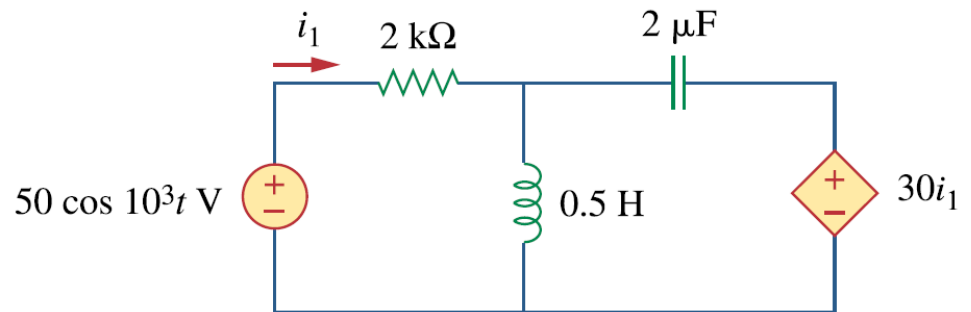
### Example – 6

Determine  $v_0$  in this circuit.



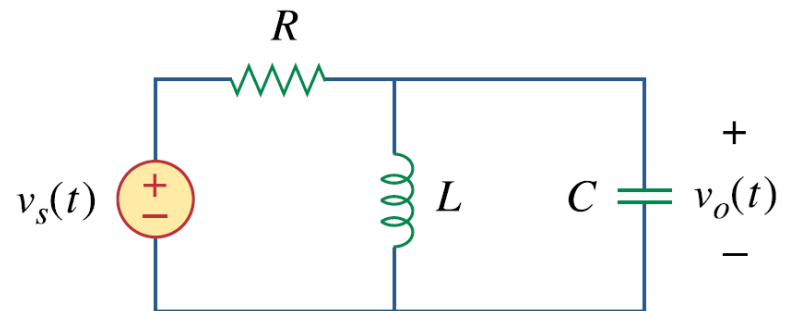
### Example – 7

Determine  $i_1$  in this circuit.



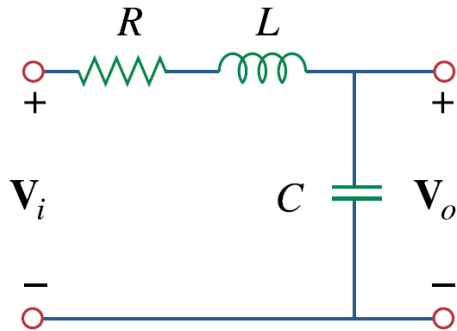
### Example – 8

In this circuit if  $v_s(t) = V_m \sin \omega t$  and  $v_o(t) = A \sin(\omega t + \varphi)$ , derive the expressions for  $A$  and  $\varphi$ .



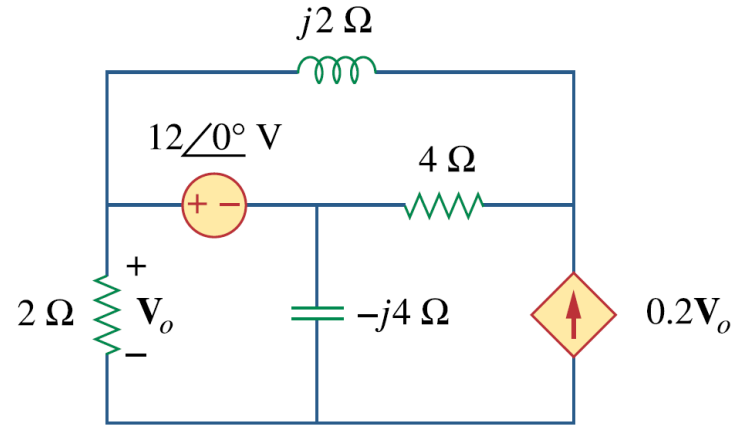
## Example – 9

Find  $V_o/V_i$  for  $\omega = 0, \omega \rightarrow \infty$   
and  $\omega^2 = 1/LC$ .

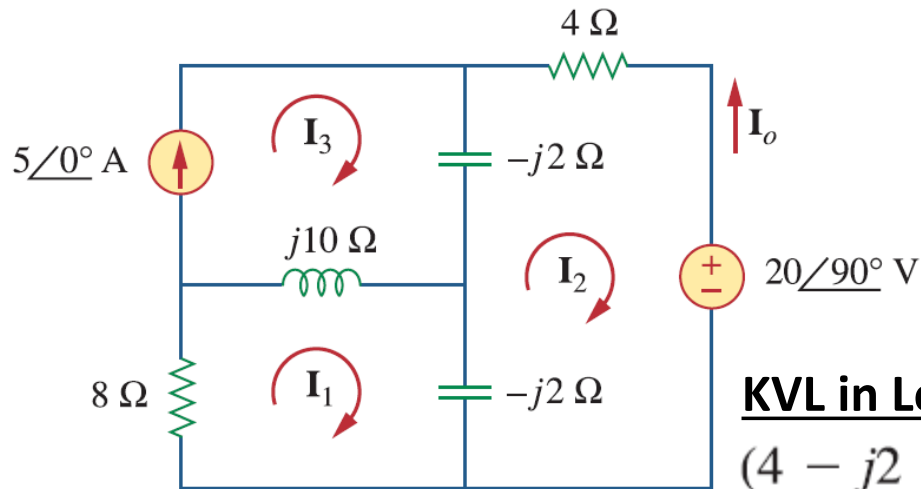


## Example – 10

Use nodal analysis to find  $V_o$ .



**Mesh Analysis** → Determine  $I_o$  using Mesh Analysis.



**in Loop 3:**  $I_3 = 5$

**KVL in Loop 1:**

$$(8 + j10 - j2)I_1 - (-j2)I_2 - j10I_3 = 0$$

**KVL in Loop 2:**

$$(4 - j2 - j2)I_2 - (-j2)I_1 - (-j2)I_3 + 20\angle 90^\circ = 0$$

## Mesh Analysis (contd.)

$$(8 + j8)\mathbf{I}_1 + j2\mathbf{I}_2 = j50$$

$$j2\mathbf{I}_1 + (4 - j4)\mathbf{I}_2 = -j20 - j10$$

$$\begin{bmatrix} 8 + j8 & j2 \\ j2 & 4 - j4 \end{bmatrix} \begin{bmatrix} \mathbf{I}_1 \\ \mathbf{I}_2 \end{bmatrix} = \begin{bmatrix} j50 \\ -j30 \end{bmatrix}$$

$$\Delta = \begin{vmatrix} 8 + j8 & j2 \\ j2 & 4 - j4 \end{vmatrix} = 32(1 + j)(1 - j) + 4 = 68$$

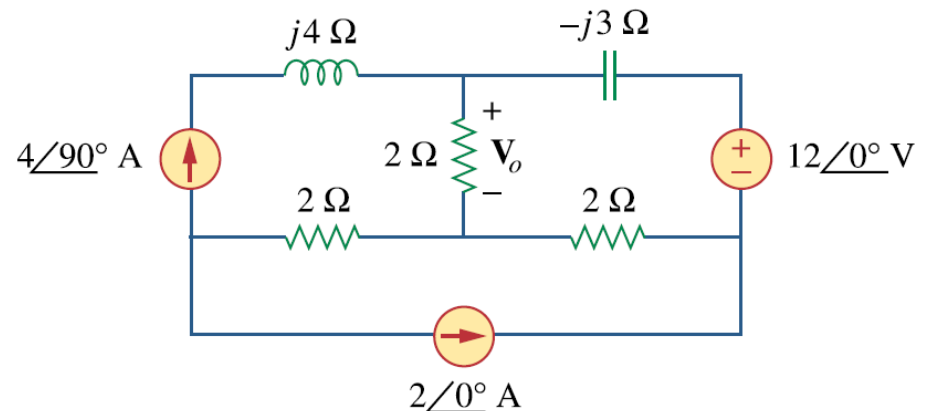
$$\Delta_2 = \begin{vmatrix} 8 + j8 & j50 \\ j2 & -j30 \end{vmatrix} = 340 - j240 = 416.17 \angle -35.22^\circ$$

$$\mathbf{I}_2 = \frac{\Delta_2}{\Delta} = \frac{416.17 \angle -35.22^\circ}{68} = 6.12 \angle -35.22^\circ \text{ A}$$

$$\mathbf{I}_o = -\mathbf{I}_2 = 6.12 \angle 144.78^\circ \text{ A}$$

### Example – 11

- Use mesh analysis to find  $v_o$ .

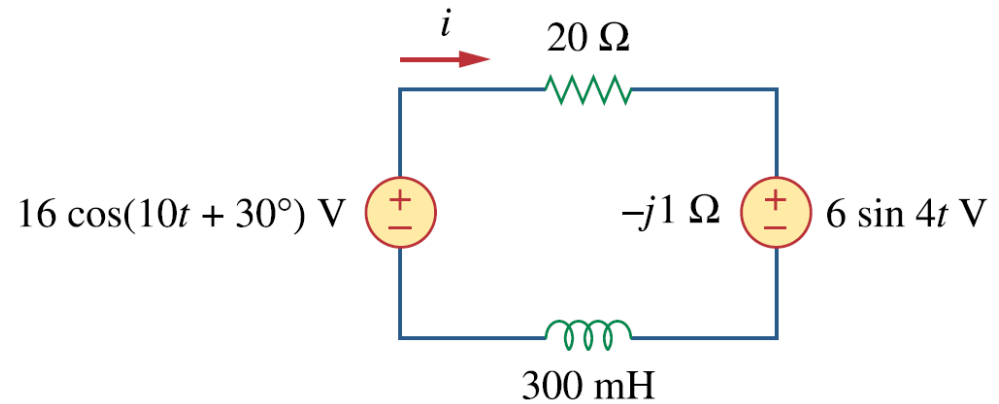


## Superposition Theorem

- These circuits are linear and hence you can apply superposition theorem.
- If sources have different frequencies then individual response must be added in the time domain.
- You can't add them in phasors as they have different  $e^{j\omega t}$ .

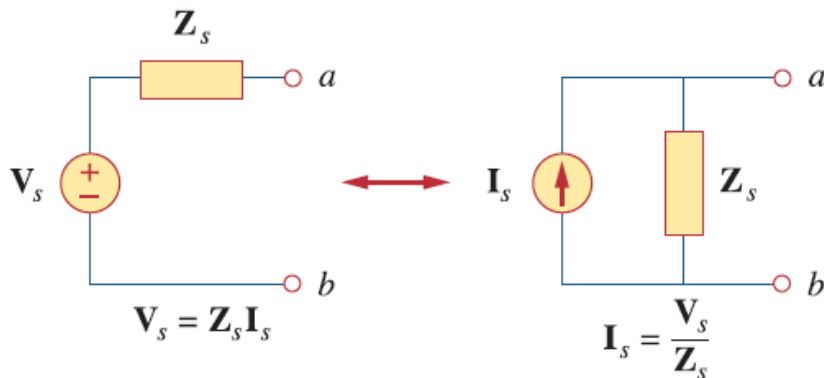
## Example – 12

- Use superposition to find  $i(t)$ .



## Source Transformation

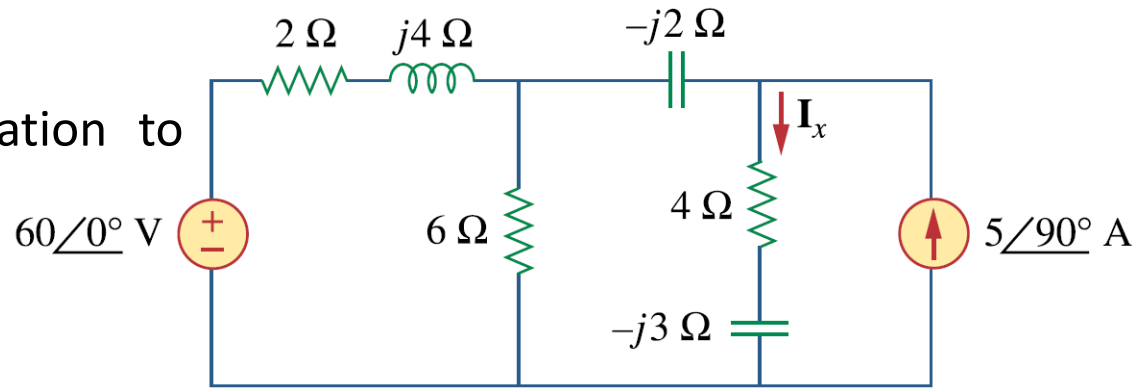
It involves transformation of **voltage source in series with an impedance** to a **current source in parallel with an impedance**, or vice versa.



$$V_s = Z_s I_s \quad \Leftrightarrow \quad I_s = \frac{V_s}{Z_s}$$

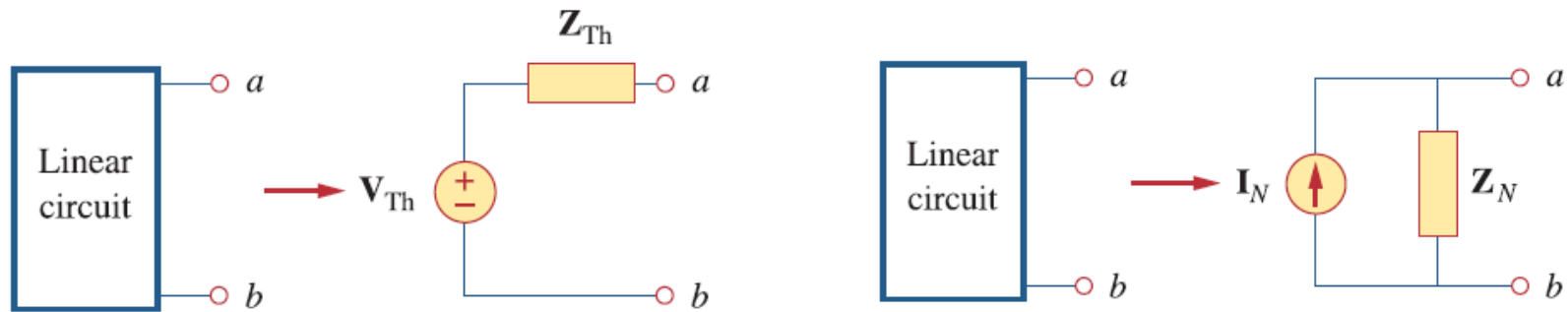
## Example – 13

- Use source transformation to find  $I_x$ .



## Thevenin and Norton Equivalent Circuits

- These theorems are applied to AC circuits similar to the way it is applied to DC circuits.
- You need to work with complex numbers in AC circuits.
- For sources with different frequencies, you will have different equivalent circuit for each frequency.

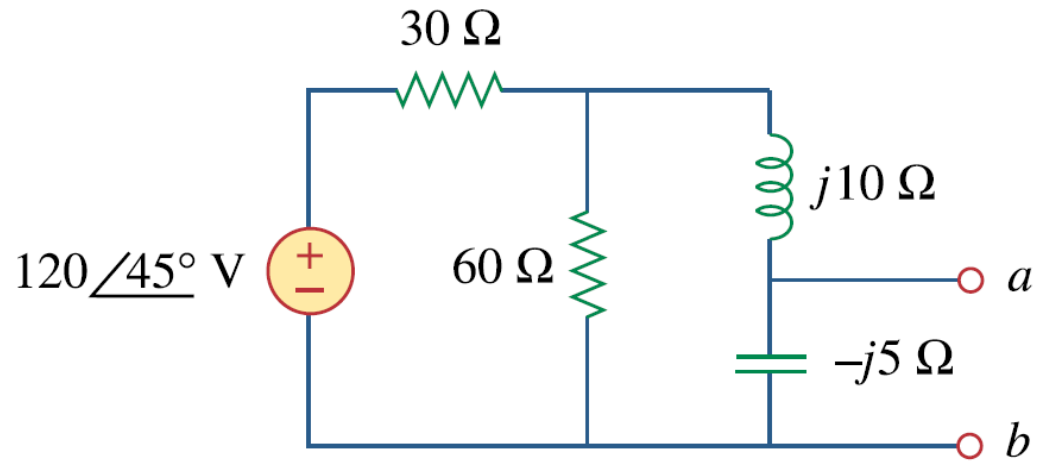


$$V_{Th} = Z_N I_N,$$

$$Z_{Th} = Z_N$$

## Example – 14

- Obtain Thevenin and Norton equivalent circuits at terminal a-b.



## Example – 15

- Using Thevenin Theorem, determine  $v_o(t)$ .

