# <u>Lecture – 15</u>

# Date: 26.09.2017

• Frequency Response (Contd.)

# Introduction

- In sinusoidal circuit analysis, we learnt how to find voltages and currents in a circuit with a constant frequency source.
- For <u>fixed amplitude</u> and <u>variable frequency</u> of the sinusoidal source → one can obtain the circuit's *frequency response*.
- <u>Frequency Response</u> is a <u>complete description</u> of the sinusoidal steadystate behavior of a circuit <u>as a function of frequency</u>.
- <u>Sinusoidal Steady-State frequency responses</u> are of significance in many applications, especially in communications and control systems.
- Electric Filters utilizes Freq Response → eliminate signals with unwanted frequencies and pass signals of the desired frequencies.
- Filters are used in radio, TV, and telephone systems to separate one broadcast frequency from another.

#### **Transfer Function**

- transfer function (also called the *network function*)  $\rightarrow$  useful analytical tool for finding the frequency response  $\rightarrow$  represented by  $H(\omega)$ .
- Circuit's frequency response is the plot of  $H(\omega)$  when  $\omega$  varies  $(0 \rightarrow \infty)$ .

$$H(\omega) = \frac{Y(\omega)}{X(\omega)}$$
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frequency-dependent ratio of a phasor output  $\mathbf{Y}(\omega)$  to a phasor input  $\mathbf{X}(\omega)$ .

• Since the input and output can be either voltage or current at any place in the circuit, there are four possible transfer functions:

$$\mathbf{H}(\omega) = \text{Voltage gain} = \frac{\mathbf{V}_o(\omega)}{\mathbf{V}_i(\omega)} \qquad \qquad \mathbf{H}(\omega) = \text{Current gain} = \frac{\mathbf{I}_o(\omega)}{\mathbf{I}_i(\omega)}$$
$$\mathbf{H}(\omega) = \text{Transfer Impedance} = \frac{\mathbf{V}_o(\omega)}{\mathbf{I}_i(\omega)} \qquad \qquad \mathbf{H}(\omega) = \text{Transfer Admittance} = \frac{\mathbf{I}_o(\omega)}{\mathbf{V}_i(\omega)}$$

Being a complex quantity,  $H(\omega)$  has a magnitude  $H(\omega)$  and a phase  $\varphi$ .

# **Transfer Function (contd.)**

- transfer function of a circuit can be obtained by first converting it to frequency-domain equivalent by replacing resistors, inductors, and capacitors with their impedances R,  $j\omega L$  and  $^{1}/_{i\omega C}$ .
- use any circuit technique(s) to obtain the appropriate expressions.
- Can be simplified to:  $\mathbf{H}(\omega) = \frac{\mathbf{N}(\omega)}{\mathbf{D}(\omega)}$

The roots of  $N(\omega)$  are called the zeros and are usually represented as  $j\omega = z_1, z_2, \dots$  ...Similarly, the roots of  $D(\omega)$  are the *poles* and are represented as  $j\omega = p_1, p_2, \dots$  ...

A zero is a value that results in a zero value of the function. A pole is a value for which the function is infinite.

To avoid complex algebra, it is expedient to replace temporarily  $j\omega$  with s when working with  $\mathbf{H}(\omega)$  and replace s with  $j\omega$  at the end.

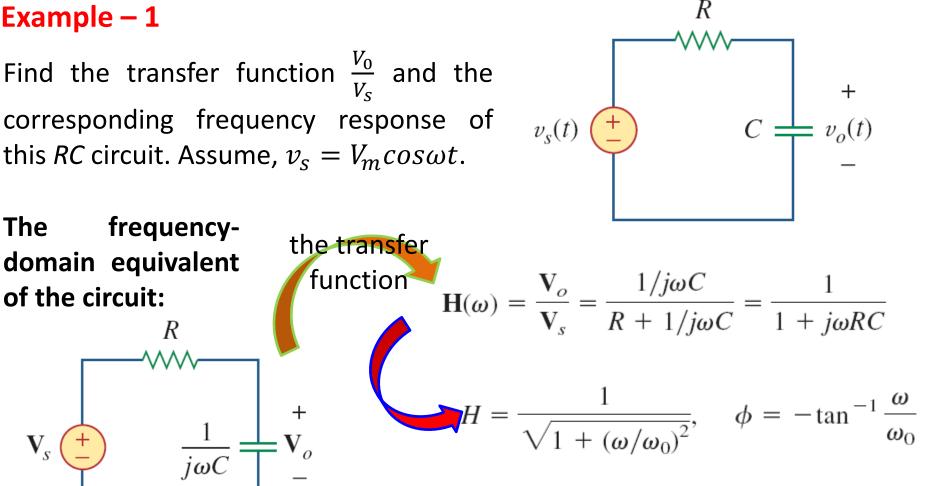
#### Example – 1

of the circuit:

R

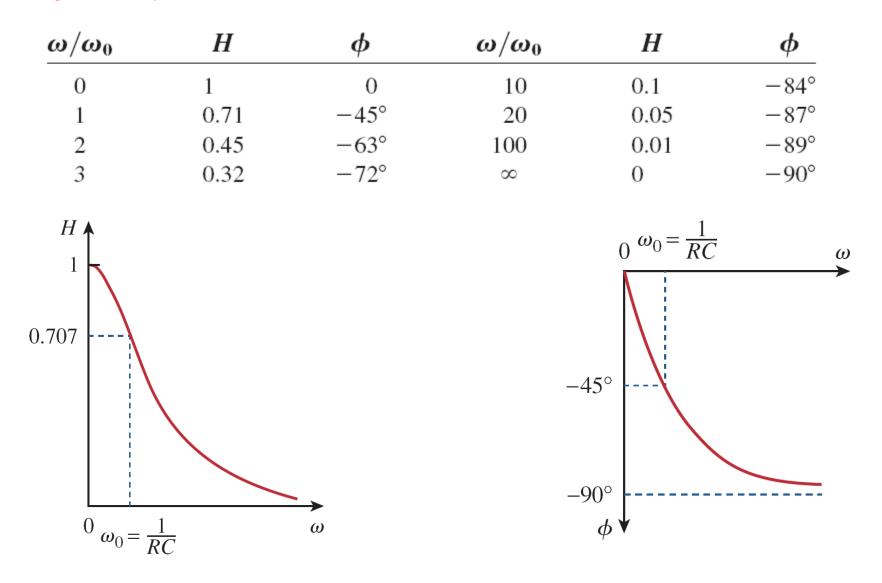
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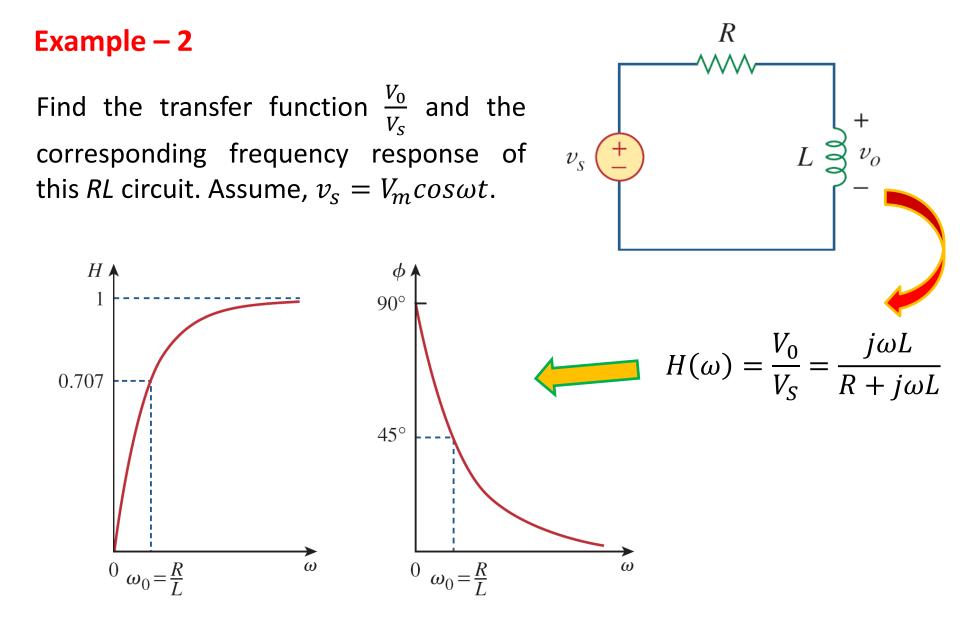
Find the transfer function  $\frac{V_0}{V_s}$  and the corresponding frequency response of this *RC* circuit. Assume,  $v_s = V_m cos \omega t$ .



where  $\omega_0 = \frac{1}{RC}$  . For plotting *H* and  $\varphi$  for  $0 < \omega < 0$  $\infty$ , we need values at some critical points.

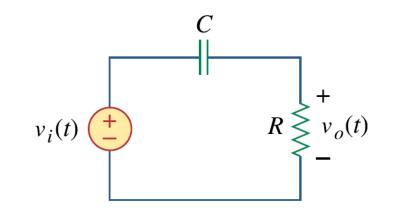
Example – 1 (contd.





#### Example – 3

Find the transfer function  $\frac{V_0}{V_s}$  and the corresponding frequency response of this *RC* circuit. Assume,  $\omega_0 = \frac{1}{RC}$ .



(b)

#### Example – 4

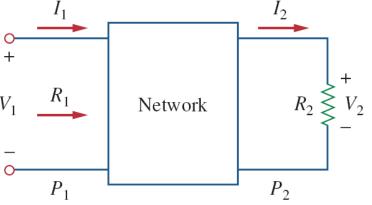
Find the transfer function  $\frac{V_0}{V_i}$  of the following circuits. CL000 + ╋ R $\mathbf{V}_i$  $\mathbf{V}_o$  $\mathbf{V}_i$  $\mathbf{V}_o$ R С  $\widetilde{\mathfrak{Z}}L$ (a)

# **Decibel Scale**

- It is not always easy to get a quick plot of the magnitude and phase of the transfer function.
- A more systematic way of obtaining the frequency response is to use Bode plots (based on logarithms).  $I_1$   $I_2$
- The bel is used to measure the ratio of two levels of power or power gain *G*:

G = number of bels =  $log_{10} \frac{P_2}{P_4}$ 

• The *decibel* (dB) provides us with a unit of less magnitude. It is 1/10<sup>th</sup> of a bel:



$$G_{dB} = 10 \log_{10} \frac{P_2}{P_1}$$

For  $P_2 = P_1$ , the gain is OdB. If  $P_2 = 2P_1$  then gain = 3dB while for  $P_2 = 0.5P_1$  the gain is -3dB

• In voltage or current ratio:  $G_{dB} = 20 log_{10} \frac{V_2}{V_1}$   $G_{dB} = 20 log_{10} \frac{I_2}{I_1}$ 

# **Decibel Scale (contd.)**

- We use 10log<sub>10</sub> for power and 20log<sub>10</sub> for voltage or current, because of the square relationship between them.
- The *dB* value is a logarithmic measurement of the *ratio* of one variable to another *of the same type* → can only be applied when the transfer function *H* is expressed as ratio of same quantities.
- so far we only used voltage and current magnitudes in above equations. Negative signs and angles will be handled independently.

With this in mind, we can apply the concepts of logarithms and decibels to construct Bode plots.

#### Example – 5

Calculate  $|H(\omega)|$  if  $H_{dB}$  equals: (a) 0.05 dB (b) -6.2 dB (c) 104.7 dB

#### Example – 6

Determine the magnitude (in dB) and the phase (in degrees) of  $H(\omega)$  at  $\omega = 1$  if  $H(\omega)$  equals: (a) 0.05 (b) 125 (c)  $\frac{10j\omega}{2+i\omega}$  (d)  $\frac{3}{1+i\omega} + \frac{6}{2+i\omega}$ 

### **Bode Plot**

- Obtaining the Freq Response from  $H(\omega)$  is extremely tedious as the frequency range required in frequency response is often so wide that it is inconvenient to use a linear scale for the frequency axis.
- Further, there is a more systematic way of locating the important features of the magnitude and phase plots of the transfer function using semilogarithmic plots known as *Bode Plot*.
- In **Bode Plot**, the magnitude in decibels is plotted against the logarithm of the frequency; on a separate plot, the phase in degrees is plotted against the logarithm of the frequency.

 $\mathbf{H} = H/\phi = He^{j\phi} \qquad \mathbf{I} = \ln \mathbf{H} + \ln e^{j\phi} = \ln \mathbf{H} + j\phi$ 

# the real part is a function of the magnitude while the imaginary part is the phase.

• In a Bode plot, magnitude is plotted in decibels (dB) vs frequency while the phase is plotted in degrees vs frequency on a semilog scale.

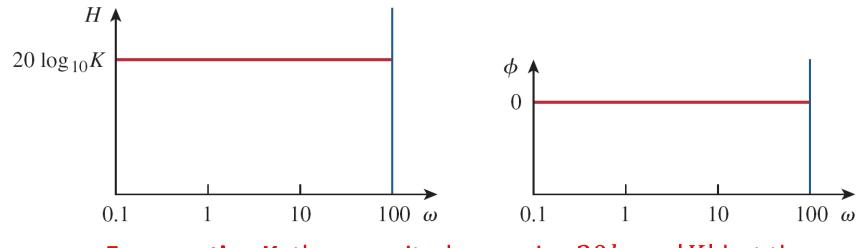
A generic transfer function:

$$\mathbf{H}(\boldsymbol{\omega}) = \frac{K(j\boldsymbol{\omega})^{\pm 1} \left(1 + j\boldsymbol{\omega}/z_1\right) \left[1 + j2\zeta_1 \boldsymbol{\omega}/\boldsymbol{\omega}_k + (j\boldsymbol{\omega}/\boldsymbol{\omega}_k)^2\right] \cdots}{\left(1 + j\boldsymbol{\omega}/p_1\right) \left[1 + j2\zeta_2 \boldsymbol{\omega}/\boldsymbol{\omega}_n + (j\boldsymbol{\omega}/\boldsymbol{\omega}_n)^2\right] \cdots}$$

This generic formulation may include up to seven types of different factors that can appear in various combinations.

- A gain K
- A pole  $(j\omega)^{-1}$  or zero  $(j\omega)$  at the origin
- A simple pole  $\frac{1}{(1+j\omega/p_1)}$  or zero  $(1+j\omega/z_1)$  A quadratic pole  $\frac{1}{[1+j2\zeta_2\omega]} + (j\omega)^2$  or zero  $\left[1+\frac{j2\zeta_1\omega}{\omega_k} + (j\omega)^2\right]$
- The Bode plot is constructed by plotting each factor separately and • then by subsequent addition.

**<u>Constant term</u>**: For K, the magnitude is  $20log_{10}K$  and the phase angle is  $0^{\circ}$ 



For negative K, the magnitude remains  $20log_{10}|K|$  but the phase angle is  $\pm 180^{\circ}$ 

**Pole/zero at the origin:** For the zero  $(j\omega)$  at the origin, the magnitude is  $20log_{10}(\omega)$  and the phase is 90°.

 slope of the magnitude plot is 20dB/decade, while the phase is constant with frequency.

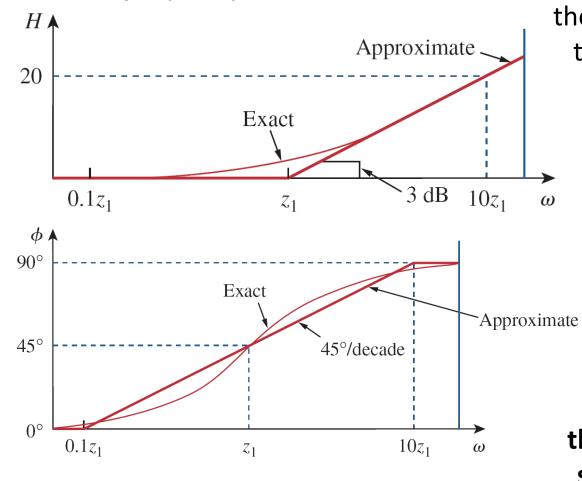


The Bode plots for the pole  $(j\omega)^{-1}$  are similar except that the slope of the magnitude plot is -20dB/decade while the phase is  $-90^{\circ}$ . In general, for  $(j\omega)^{N}$  where N is an integer, the magnitude plot will have a slope of 20N dB/decade, while the phase is 90N degrees.

Simple pole/zero: 
$$(1 + \frac{j\omega}{z_1}) = 0$$
 as  $\omega \to 0$   
 $H_{\rm dB} = 20 \log_{10} \left| 1 + \frac{j\omega}{z_1} \right| = 20 \log_{10} \frac{\omega}{z_1}$  as  $\omega \to \infty$ 

 It shows that we can approximate the magnitude as zero (a straight line with zero slope) for small values of ω and by a straight line with slope 20 dB/decade for large values of ω.

• The frequency  $\omega = z_1$  where the two asymptotic lines meet is called the *corner frequency* or *break frequency*.

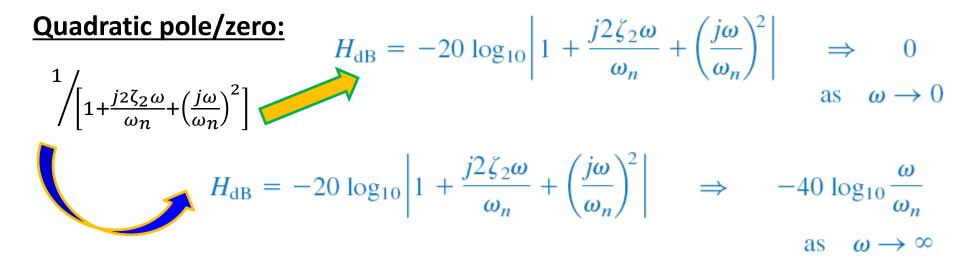


$$\phi = \tan^{-1} \left( \frac{\omega}{z_1} \right) = \begin{cases} 0, & \omega = 0\\ 45^\circ, & \omega = z_1\\ 90^\circ, & \omega \to \infty \end{cases}$$

the approximate plot is close to the actual plot except at the break frequency ( $\omega = z_1$ ), where the deviation is  $20log_{10}|1+j1| =$  $20log_{10}|\sqrt{2}| \approx 3dB.$ As straight-line а approximation we let:  $\varphi \cong 0^{\circ}$  for  $\omega \leq \frac{z_1}{10}$  $\varphi \cong 45^\circ$  for  $\omega = z_1$  $\varphi \cong 90^\circ$  for  $\omega \ge 10z_1$ 

the straight-line plot has a slope of  $45^{\circ}$  per decade.

• The Bode plots for the pole  $\frac{1}{(1+j\omega/p_1)}$  are similar except that the corner frequency is at  $\omega = p_1$ , the magnitude has a slope of -20 dB/decade and the phase has a slope of  $-45^\circ$  per decade.



Clearly, the amplitude plot consists of two straight asymptotic lines: one with zero slope for  $\omega < \omega_n$  and the other with slope  $-40 \ dB$ /decade for  $\omega > \omega_n$  with  $\omega_n$  as the corner frequency.