

Lecture-12

Date: 01.10.2015

- Differential Amplifier

Differential Amplifier

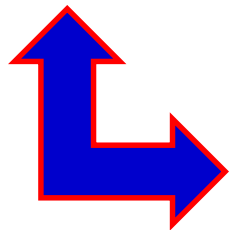
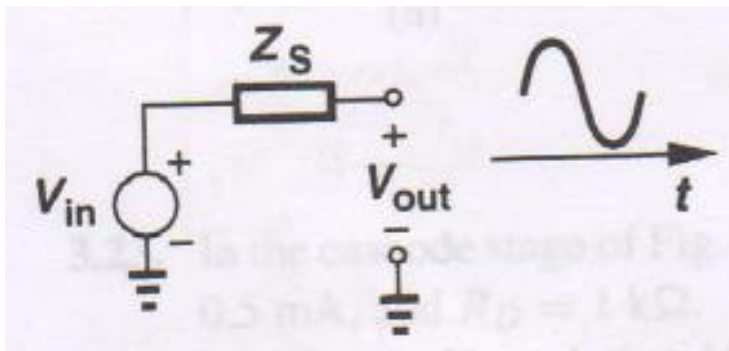
- **Why differential?**
- **What do we want from an amplifier?**
 - **robust operation** → free from external effects such as noise
 - **High output voltage swing** → optimal headroom / legroom
 - **High gain** → such as cascode configuration
 - **Linear Performance**
- **Differential amplifiers exhibit/provide following features:**
 - **robust operation** → noise do not affect its performance
 - **Higher output voltage swing**
 - **Higher gain in comparison to single-stage amplifiers**
 - **Linear Performance and simpler biasing**

Major Drawback: more area on a chip (however not always true!)

Differential Amplifier (contd.)

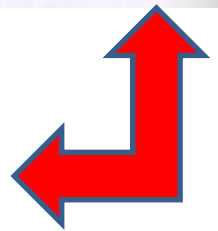
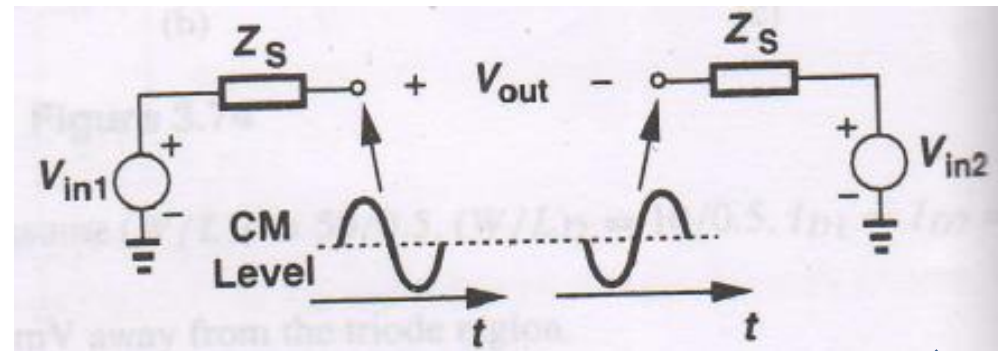
Differential amplifier deals with differential signals

Single-ended signals



Defined with respect to a fixed potential (usually ground)

Differential signals



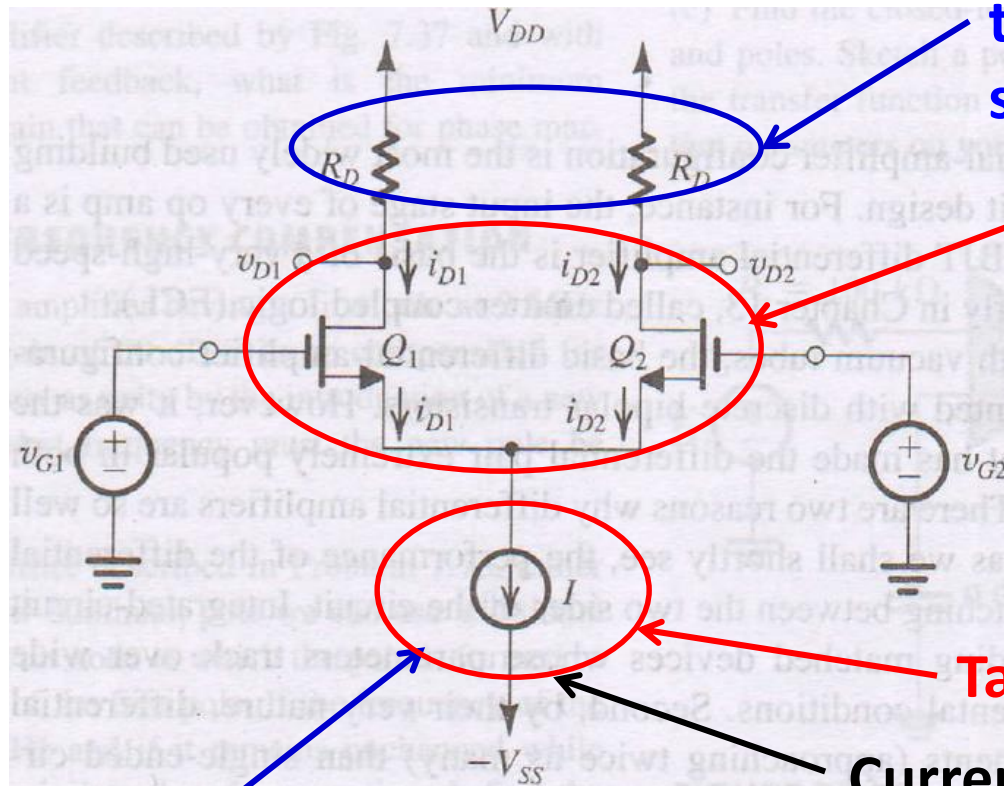
Defined between two nodes that have equal and opposite signal excursions around a fixed potential



The fixed potential in differential signal is called "common-mode" CM level

Differential Amplifier (contd.)

MOS Differential Pair



Loads (active!) → must ensure that the transistors remain in saturation

These transistors are perfectly matched (at least in theory!)

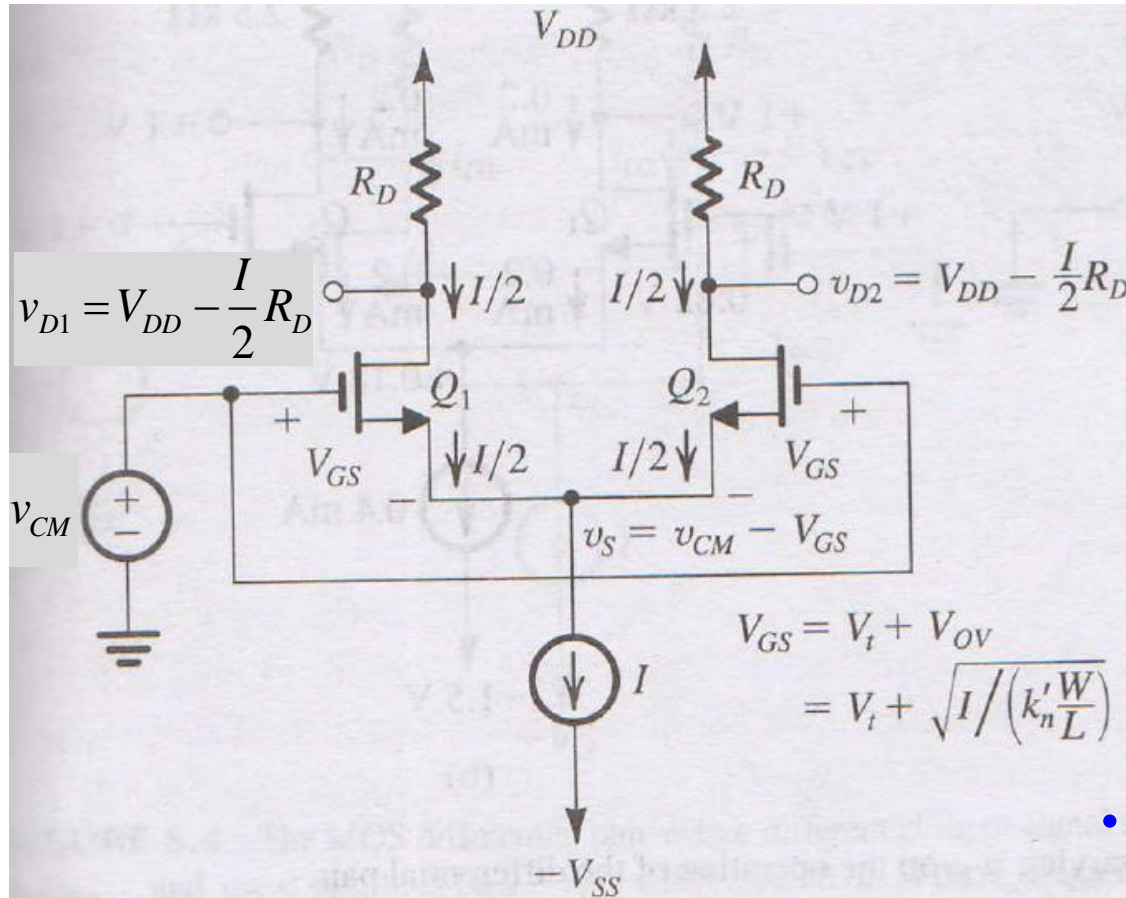
Tail Current

Current source is ideal: constant current, infinite output impedance

What is the need?

-to overcome the issues emanating from non-ideal CM level

Operation with a Common-Mode Input Voltage



$$v_{G1} = v_{G2} = v_{CM}$$

- Since Q1 and Q2 are matched, the symmetry gives:

$$i_{D1} = i_{D2} = \frac{I}{2}$$

- Source Voltage is:

$$v_s = v_{CM} - V_{GS}$$

- Where, V_{GS} is obtained from:

$$\frac{I}{2} = \frac{1}{2} \mu_n C_{ox} \left(\frac{W}{L} \right) (V_{GS} - V_T)^2$$

- Voltage at each drain is: $v_{D1} = v_{D2} = V_{DD} - \frac{I}{2}R_D$

Operation with a Common-Mode Input Voltage (contd.)

- **Drain Voltage Difference:** $v_o = v_{D1} - v_{D2} = 0$
- Voltage difference is zero \rightarrow what does it suggest?
 - The differential pair doesn't respond to CM input signals
- **Let us look further:** suppose v_{CM} is varied in such a way that Q_1 and Q_2 remain in saturation \rightarrow "I" will divide equally between Q_1 and Q_2 \rightarrow the drain voltages (v_{D1} and v_{D2}) will not change \rightarrow difference in drain voltages will remain zero
 - This clearly supports the hypothesis that the differential pair doesn't respond to CM input signals \rightarrow alternatively, differential pair rejects variations in CM input signals \rightarrow provides protection against any abrupt changes in CM level originating from any factors such as noise etc.
- How about the common-mode input range? \rightarrow The range of v_{CM} over which Q_1 and Q_2 operate properly

Operation with a Common-Mode Input Voltage (contd.)

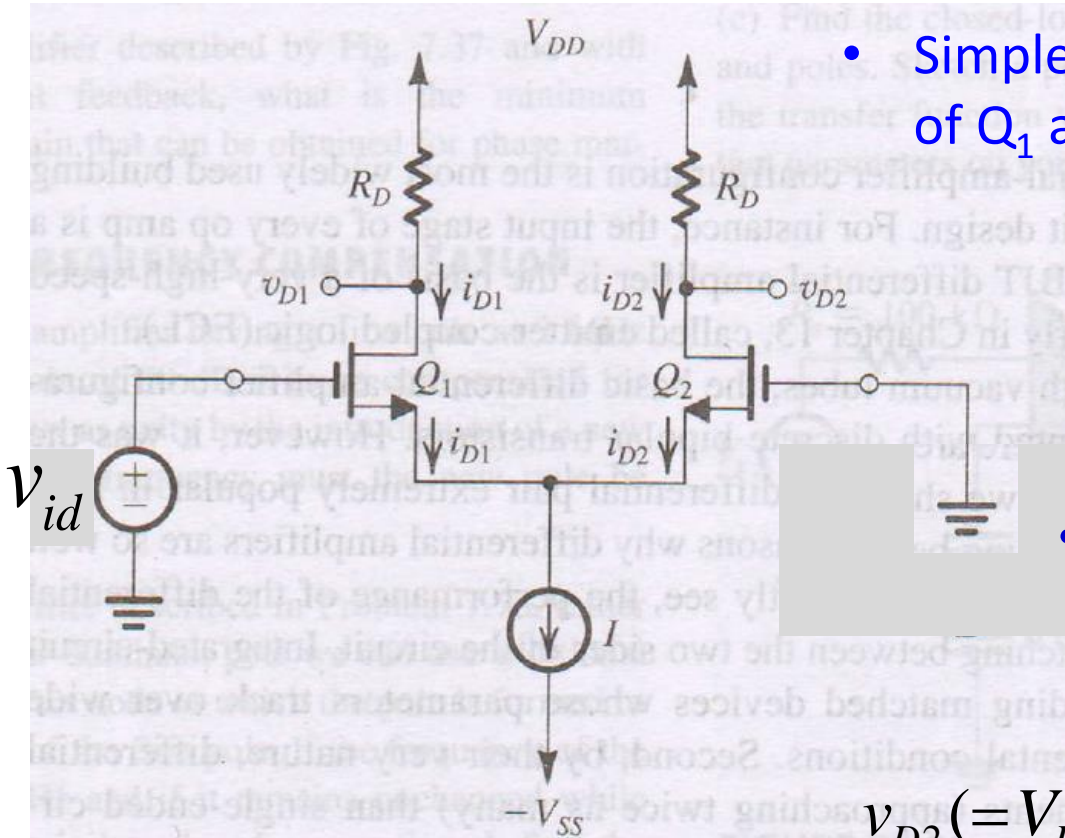
- For Q_1 and Q_2 to remain in saturation:

$$\begin{aligned}
 V_{GS} - V_T &\leq V_{DS} &\Rightarrow (v_{CM} - v_S) - V_T &\leq V_{DD} - \frac{I}{2}R_D - v_S \\
 \Rightarrow v_{CM} &\leq V_T + V_{DD} - \frac{I}{2}R_D &\therefore (v_{CM})_{\max} &= V_T + V_{DD} - \frac{I}{2}R_D
 \end{aligned}$$

- The lowest value of v_{CM} is determined by the need to keep the constant current source operational:

$$\begin{aligned}
 v_{CM} - V_{GS} - (-V_{SS}) &\geq V_{CS} &\Rightarrow v_{CM} - V_{GS} + V_T - V_T &\geq -V_{SS} + V_{CS} \\
 \Rightarrow v_{CM} - V_{OV} - V_T &\geq -V_{SS} + V_{CS} &\Rightarrow v_{CM} &\geq -V_{SS} + V_{CS} + V_{OV} + V_T \\
 \therefore (v_{CM})_{\min} &= -V_{SS} + V_{CS} + V_{OV} + V_T
 \end{aligned}$$

Operation with a Differential Input Voltage



- Simple differential input: v_{id} to the gate of Q_1 and grounding of gate of Q_2 :

$$v_{GS1} = v_{id} - v_s$$

$$v_{GS2} = -v_s$$

$$v_{id} = v_{GS1} - v_{GS2}$$

- For +ve $v_{id} \rightarrow v_{GS1}$ is greater
 $\rightarrow i_{D1}$ will be greater than i_{D2}



$$v_{D2} (= V_{DD} - i_{D2} R_D) > v_{D1} (= V_{DD} - i_{D1} R_D)$$



- Differential output voltage: $v_{D2} - v_{D1} > 0$

Operation with a Differential Input Voltage (contd.)

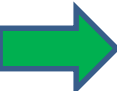
- For -ve $v_{id} \rightarrow v_{GS2}$ is greater $\rightarrow i_{D2}$ will be greater than i_{D1}



$$v_{D2} (= V_{DD} - i_{D2} R_D) < v_{D1} (= V_{DD} - i_{D1} R_D)$$



Differential output voltage: $v_{D2} - v_{D1} < 0$

 It is thus apparent that the differential pair respond to differential-mode signals \rightarrow by providing differential output signal between the two drains

Operation with a Differential Input Voltage (contd.)

- Differential pair as an amplifier
- **Consider the scenario: (for small v_{id})**
 - For +ve v_{id} , a small increase of v_{id} will bring an increase of ΔI in the current “I” through Q_1 and a decrease by same amount in current “I” through Q_2 .

Therefore:

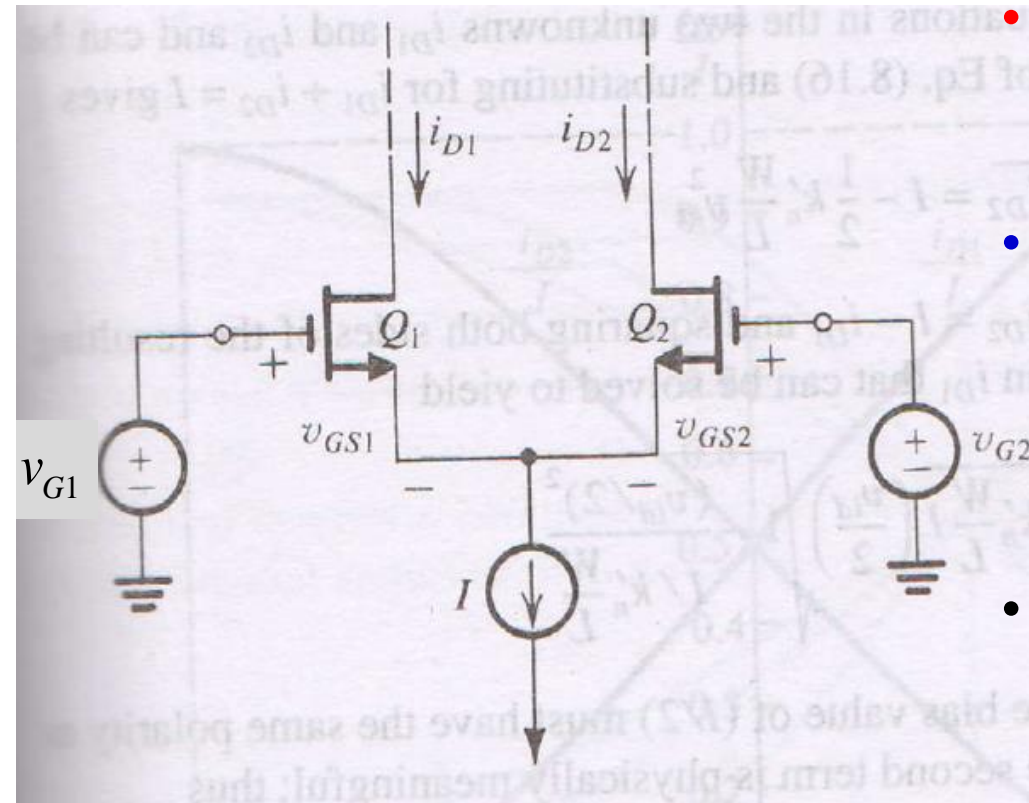
$-\Delta I R_D$: develops at the drain of Q_1

$\Delta I R_D$: develops at the drain of Q_2

Thus, additional differential output: $\Delta v_o = 2\Delta I R_D \propto v_{id}$: develops

Amplifier Action

Differential Pair – Large-Signal Operation



- The idea is to define i_{D1} and i_{D2} in terms of input differential signal $V_{id} = V_{G1} - V_{G2}$
- The circuit doesn't include connection details considering that these drain current equations do not depend on the external circuitries
- **Assumptions:** Q_1 and Q_2 are always in saturation; differential pair is perfectly matched; channel length modulation is not present

$$i_{D1} = \frac{1}{2} \mu_n C_{ox} \frac{W}{L} (v_{GS1} - v_T)^2$$

$$i_{D2} = \frac{1}{2} \mu_n C_{ox} \frac{W}{L} (v_{GS2} - v_T)^2$$

Differential Pair – Large-Signal Operation (contd.)

$$i_{D1} = \frac{1}{2} \mu_n C_{ox} \frac{W}{L} (v_{GS1} - v_T)^2$$

$$i_{D2} = \frac{1}{2} \mu_n C_{ox} \frac{W}{L} (v_{GS2} - v_T)^2$$

$$\sqrt{i_{D1}} = \sqrt{\frac{1}{2} \mu_n C_{ox} \frac{W}{L}} (v_{GS1} - v_T)$$

$$\sqrt{i_{D2}} = \sqrt{\frac{1}{2} \mu_n C_{ox} \frac{W}{L}} (v_{GS2} - v_T)$$

$$\sqrt{i_{D1}} - \sqrt{i_{D2}} = \sqrt{\frac{1}{2} \mu_n C_{ox} \frac{W}{L}} (v_{GS1} - v_{GS2})$$

$$\sqrt{i_{D1}} - \sqrt{i_{D2}} = \sqrt{\frac{1}{2} \mu_n C_{ox} \frac{W}{L}} \cdot v_{id}$$

$$v_{GS1} - v_{GS2} = v_{G1} - v_{G2} = v_{id}$$

Differential Pair – Large-Signal Operation (contd.)

Now: $\sqrt{i_{D1}} - \sqrt{i_{D2}} = \sqrt{\frac{1}{2} \mu_n C_{ox} \frac{W}{L}} \cdot v_{id}$ and: $i_{D1} + i_{D2} = I$

$$i_{D1} = \frac{I}{2} \pm \sqrt{\mu_n C_{ox} \frac{W}{L}} I \left(\frac{v_{id}}{2} \right) \sqrt{1 - \frac{(v_{id}/2)^2}{I / (\mu_n C_{ox} \frac{W}{L})}}$$

i_{D1} has same polarity as v_{id} → here +ve

$$\therefore i_{D1} = \frac{I}{2} + \sqrt{\mu_n C_{ox} \frac{W}{L}} I \left(\frac{v_{id}}{2} \right) \sqrt{1 - \frac{(v_{id}/2)^2}{I / (\mu_n C_{ox} \frac{W}{L})}}$$

$$\Rightarrow i_{D2} = I - i_{D1} = \frac{I}{2} - \sqrt{\mu_n C_{ox} \frac{W}{L}} I \left(\frac{v_{id}}{2} \right) \sqrt{1 - \frac{(v_{id}/2)^2}{I / (\mu_n C_{ox} \frac{W}{L})}}$$

Differential Pair – Large-Signal Operation (contd.)

- **At bias point:** $v_{id} = 0 \quad \Rightarrow \quad i_{D1} = i_{D2} = \frac{I}{2}$

$$v_{GS1} = v_{GS2} = V_{GS} \quad \Rightarrow \quad \frac{I}{2} = \frac{1}{2} \mu_n C_{ox} \frac{W}{L} (V_{GS} - V_T)^2 = \frac{1}{2} \mu_n C_{ox} \frac{W}{L} (V_{OV})^2$$

- **Therefore:**

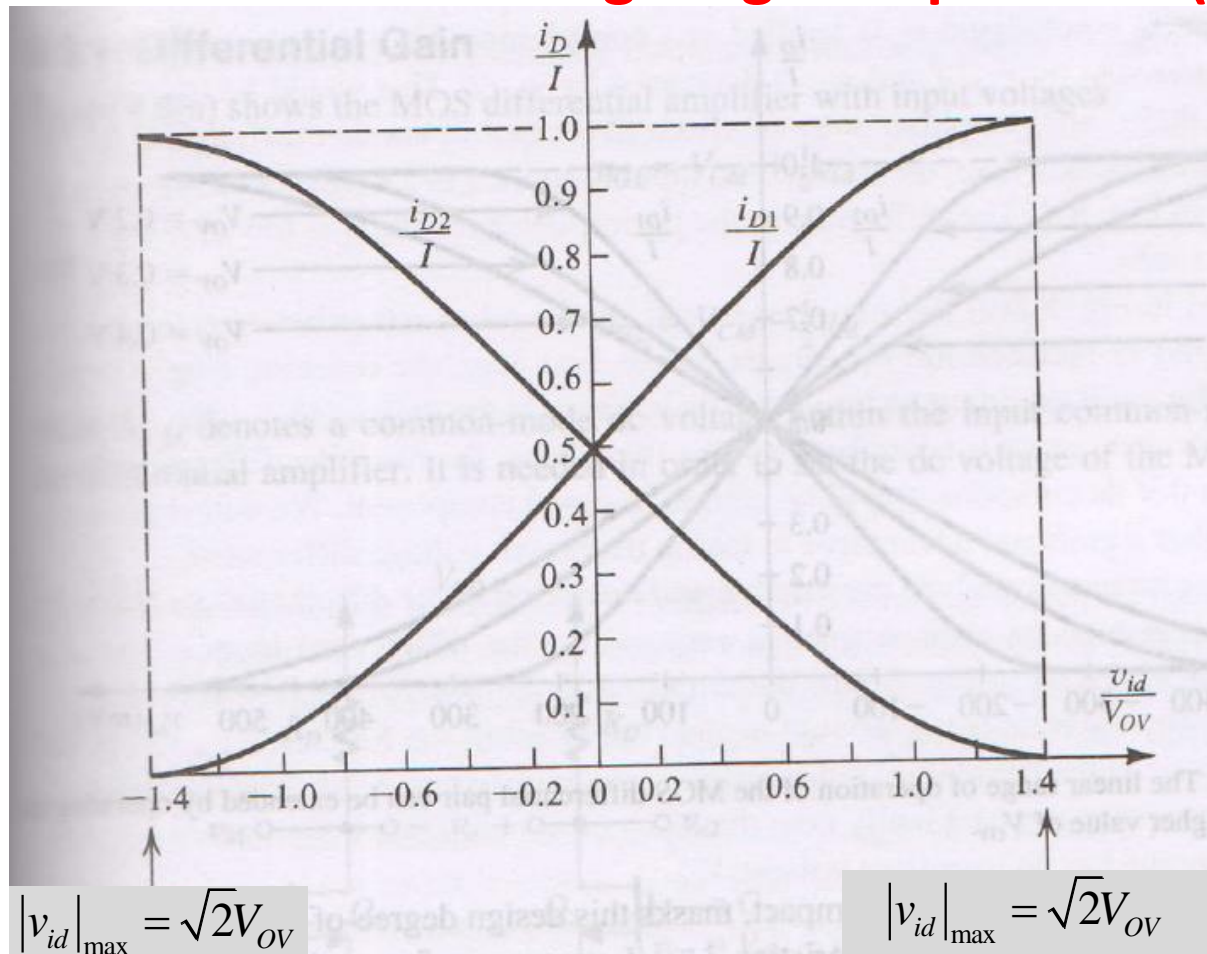
$$i_{D1} = \frac{I}{2} + \left(\frac{I}{V_{OV}} \right) \left(\frac{v_{id}}{2} \right) \sqrt{1 - \frac{(v_{id}/2)^2}{V_{OV}^2}}$$

$$i_{D2} = \frac{I}{2} - \left(\frac{I}{V_{OV}} \right) \left(\frac{v_{id}}{2} \right) \sqrt{1 - \frac{(v_{id}/2)^2}{V_{OV}^2}}$$

Drain currents in terms of v_{id}

Basically describes the effect of differential input on drain currents

Differential Pair – Large-Signal Operation (contd.)



V_{OV} : overdrive voltage for Q_1 and Q_2 for $I/2$.

$i_{D1} = i_{D2} = I/2$: for $v_{id} = 0$

Making v_{id} +ve causes i_{D1} to increase while making v_{id} -ve causes i_{D2} to increase

$v_{id} = \sqrt{2}V_{OV}$: the current I is steered through Q_1

$v_{id} = -\sqrt{2}V_{OV}$: the current I is steered through Q_2

Differential Pair – Large-Signal Operation (contd.)

Observations:

- The currents are nonlinear due to presence of square term
- Our interest: linear amplification \leftrightarrow how to achieve that?
- By keeping $(v_{id}/2)$ much smaller than V_{OV}

$$i_{D1} = \frac{I}{2} + \left(\frac{I}{V_{OV}} \right) \left(\frac{v_{id}}{2} \right) \sqrt{1 - \frac{(v_{id}/2)^2}{V_{OV}^2}} \cong \frac{I}{2} + \left(\frac{I}{V_{OV}} \right) \left(\frac{v_{id}}{2} \right) = \frac{I}{2} + i_d$$

$$i_{D2} = \frac{I}{2} - \left(\frac{I}{V_{OV}} \right) \left(\frac{v_{id}}{2} \right) \sqrt{1 - \frac{(v_{id}/2)^2}{V_{OV}^2}} \cong \frac{I}{2} - \left(\frac{I}{V_{OV}} \right) \left(\frac{v_{id}}{2} \right) = \frac{I}{2} - i_d$$

Where:

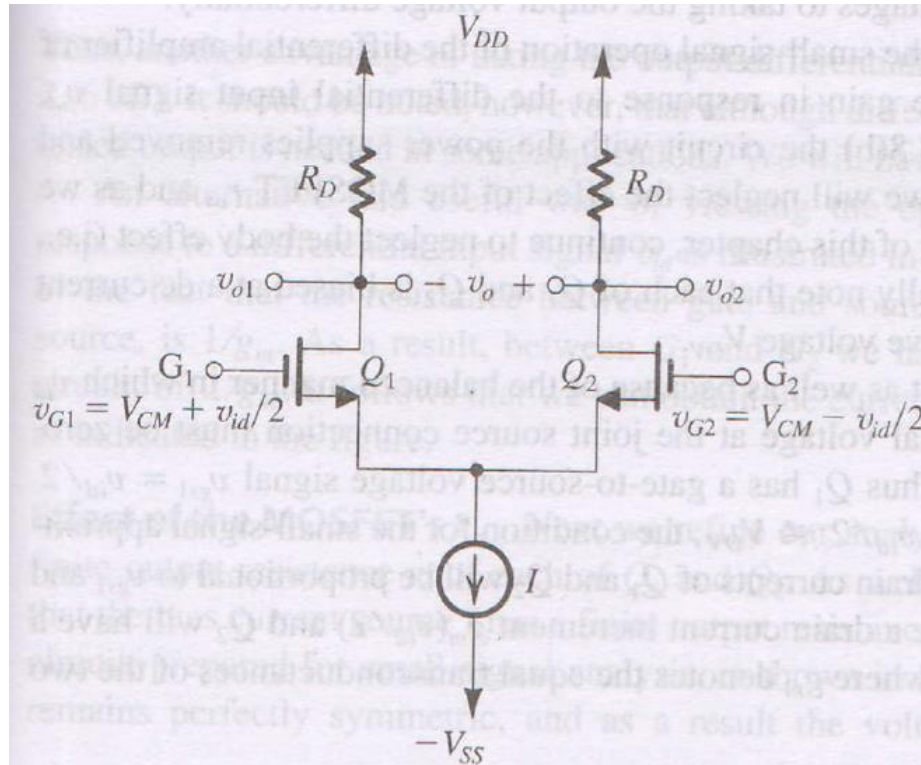
$$i_d = \left(\frac{I}{V_{OV}} \right) \left(\frac{v_{id}}{2} \right)$$

Differential Pair – Large-Signal Operation (contd.)

Observations:

- However, reduction in v_{id} leads to reduction in $g_m \rightarrow$ consequently reduction in gain
- How can we increase g_m ?
 - By using smaller $(W/L) \leftarrow$ for a constant bias current
- Linearity can also be improved by increasing $V_{OV} \rightarrow$ however this results into reduced $g_m \leftrightarrow g_m$ can be increased by increasing bias current but at the expense of higher power consumption

Differential Pair – Small-Signal Operation



Input Voltages

$$v_{G1} = v_{CM} + \frac{1}{2}v_{id}$$

$$v_{G2} = v_{CM} - \frac{1}{2}v_{id}$$

- v_{CM} is common-mode dc voltage → is needed to set the dc voltages (biasing point) of the NFETs
- In general, v_{CM} is at the middle of the power supply → therefore, for dual-rail supply it is typically zero
- The differential signal v_{id} is applied in a balanced manner → v_{G1} increases by $v_{id}/2$ and v_{G2} decreases by $v_{id}/2$

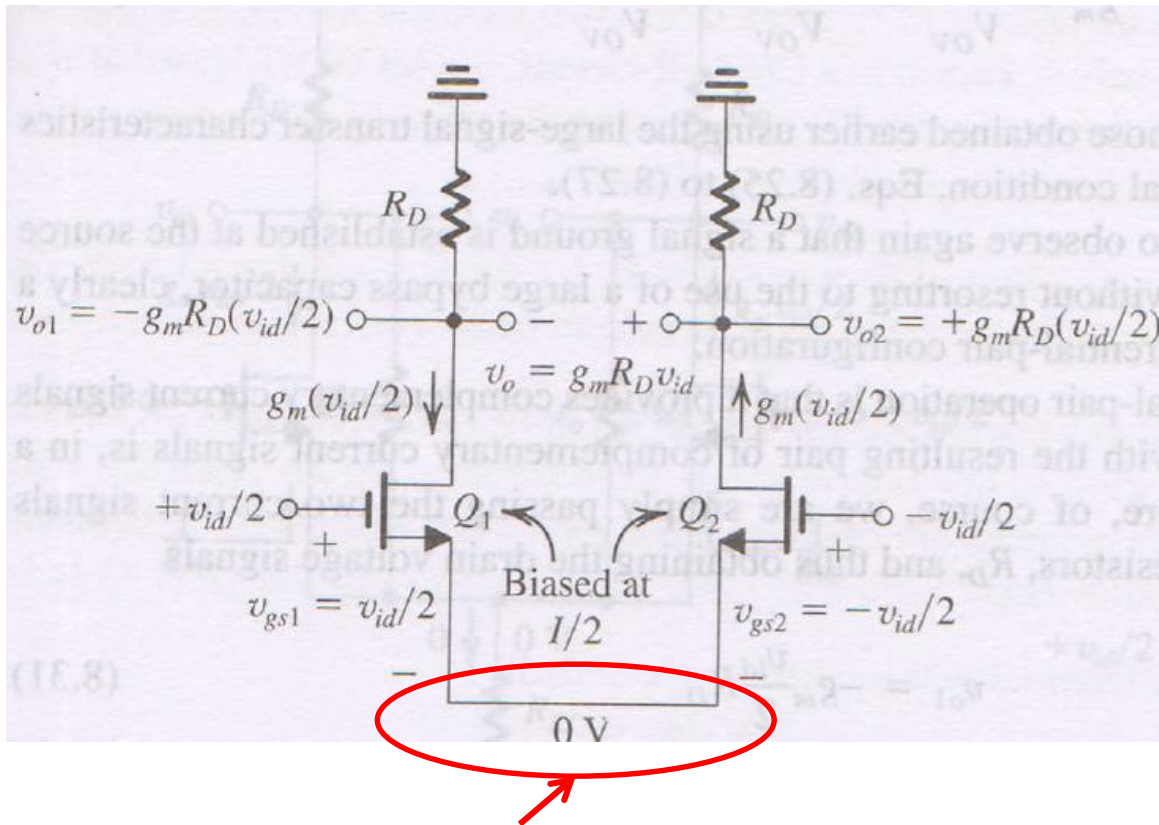
Q: Do you expect any difference in performance while applying the differential signal v_{id} in a balanced manner or in an unbalanced manner?

Differential Pair – Small-Signal Operation (contd.)

What is the small signal voltage gain?

From large-signal analysis:

$$g_m = \frac{2I_D}{V_{OV}} = \frac{2(I/2)}{V_{OV}} = \frac{I}{V_{OV}}$$



For CS mode Q_1 :

$$v_{o1} = -g_m \frac{v_{id}}{2} R_D$$

For CS mode Q_2 :

$$v_{o2} = g_m \frac{v_{id}}{2} R_D$$

Virtual Ground! → Why?



Discards the need of a bypass capacitor for ac grounding

Differential Pair – Small-Signal Operation (contd.)

For single-ended operation:

$$A_v = \frac{v_{o1}}{v_{id}} = -\frac{1}{2} g_m R_D \quad \text{OR} \quad A_v = \frac{v_{o2}}{v_{id}} = \frac{1}{2} g_m R_D$$

For differential operation:

$$A_d = \frac{v_{o2} - v_{o1}}{v_{id}} = g_m R_D \quad \leftarrow \text{Twice the single-ended gain}$$

Is it always advantageous?

